# T1: Sliding puck - Solution

When the puck moves along the wall, two forces (in addition to gravity and the normal force of the horizontal ground, which cancel each other out) act on it: the normal force of the wall (which changes the direction of motion of the puck) and the friction between the puck and the wall (which changes the speed of the puck and also causes the puck to start rotating).

So as the puck moves along the circular wall, the speed of the puck decreases and the angular velocity of the puck's rotation around its vertical axis increases. The motion of the puck is rolling with sliding along the wall. At a certain point in time t_1, the contact point of the puck *may* have zero velocity and kinetic friction becomes static. From this point onwards, the puck will be rolling without sliding along the wall.

From the zero velocity of the contact point, we find the relationship $\omega = v/r$.
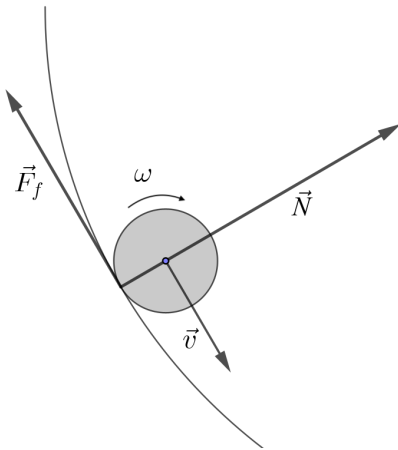
Let's focus on rolling with sliding first. The normal force $\vec{N}$ of the wall on the puck is also perpendicular to the velocity of the puck at any instantaneous position of the puck. Force $\vec{N}$ changes the direction of the velocity $\vec{v}$. From Newton's law in normal direction, we find $N = mv^2/R$, where m is the mass of the puck. Thus, the magnitude of the frictional force is $F_f = \mu N = \mu m v^2/R$.

Solution 1: The equation for the translational motion of the puck is

$$m\frac{dv}{dt} = -\mu m \frac{v^2}{R}$$

and in the integral form including the initial conditions

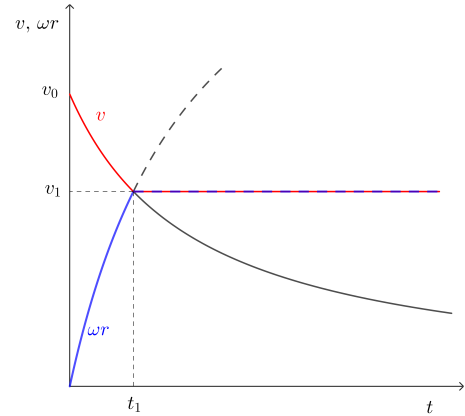$$\int_{v_0}^{v} \frac{dv}{v^2} = -\frac{\mu}{R}\int_0^t dt$$

where the time $t = 0$ is the time at which the puck meets the semicircular wall and has the initial velocity v_0. Solving the integrals gives

$$-\frac{1}{v} + \frac{1}{v_0} = -\frac{\mu}{R}t \tag{1}$$

which leads to

$$v(t) = \frac{v_0}{1 + t/\tau} \tag{2}$$

where $\tau = R/v_0\mu$. The graph drawn with the solid red line shows the time dependence of v.

The rotation of the puck around its axis of symmetry is caused by the torque of the frictional force acting on the puck at the point of contact between the puck and the wall, $M_f = rF_f = r\mu mv^2/R$, where the radius of the puck r is the arm. The equation for the rotational motion of the puck, which results from Newton's second law $Id\omega/dt = M_f$, can be written as

$$r\frac{d\omega}{dt} = \frac{\mu mr^2}{RI}v^2 = \frac{2\mu}{R}\cdot\frac{v_0^2}{(1+t/\tau)^2}$$

where $I = mr^2/2$ is the moment of inertia of the puck for rotations around its axis of symmetry and ω is the angular velocity of this rotation. The product $r\omega$ gives the relative speed of the point of contact between the puck and the wall with respect to the puck's center of mass. The integral form of this equation, including the initial conditions, is

$$r\int_0^{\omega} d\omega = \frac{2v_0}{\tau}\int_0^t \frac{dt}{(1+t/\tau)^2}$$

and the solution is

$$r\omega = v_0\frac{2t/\tau}{1+t/\tau}. \tag{3}$$

The graph of $r\omega(t)$ is drawn by the blue line.

The two solutions (2) and (3) are only valid up to the time t_1 at which the functions $v(t)$ and $r\omega(t)$ intersect, $v(t_1) = r\omega(t_1)$. At this moment, the points on the puck that touch the wall no longer move in relation to the wall and the puck no longer slides along the wall. There is no more friction. From this moment on, the motion of the puck is a frictionless translation and rotation with $v = v(t_1) = v_1$ and $\omega = v_1/r$. For t_1 we get $t_1 = \tau/2$. At t_1, the translational speed is $v_1 = 2v_0/3$.

There are two possible scenarios for the motion of the puck along the semicircular wall: it rolls with sliding along the entire wall or it starts rolling somewhere along this path without sliding. To see what happens, and also to get the exit velocity of the puck v_e, we need to calculate how the path of the puck increases with time, which is defined by equation (2), $dl/dt = v(t)$. We integrate in time from $t = 0$ to t and in distance from 0 to l and get

$$t = \tau\left(\exp\left(\frac{l}{v_0\tau}\right) - 1\right). \tag{4}$$

If we use $l_e = \pi R$, equation (4) gives the time $t_e = t(l_e) = \tau\,(\exp\pi\mu - 1)$.

If $t_e > t_1 = \tau/2$ i.e. $\pi\mu > \ln\frac{3}{2}$, then the puck starts to roll somewhere on its semicircular path along the wall without sliding and its speed when leaving the wall is $v_e = v_1 = 2v_0/3$.

If $t_e \leq t_1 = \tau/2$ i.e. $\pi\mu \leq \ln\frac{3}{2}$, then the puck still rolls with sliding when it leaves the wall, since its translational speed v_e is still greater than $2v_0/3$. The exit speed is obtained from (4) by inserting $t = t_e$,

$$v_e = v(t = t_e) = v_0 \exp(-\pi\mu). \qquad (5)$$

The graph $v_e(\mu)$ is shown in the figure.
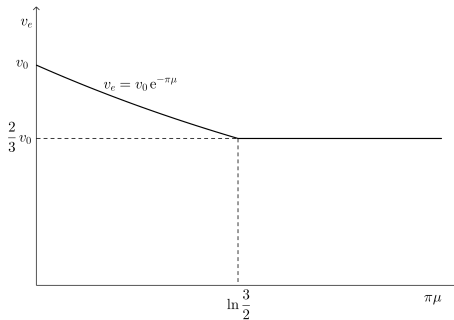
Solution 2: The equation for the translational motion of the puck is

$$m\frac{dv}{dt} = -\mu m \frac{v^2}{R}$$

which can be rewritten with $dl = v\,dt = R\,d\varphi$ as

$$\frac{dv}{v} = -\frac{\mu}{R}dl = -\mu d\varphi.$$

We recognize the dependence of v on φ;

$$v = v_0 \exp(-\mu\varphi), \qquad (6)$$

where $\varphi = 0$ at the beginning of the semicircular wall and $\varphi = \pi$ at its end. It describes the dependence of v on φ under the condition that the puck rolls and slides at the same time.

Due to the torque of the frictional force the puck also starts to roll along the wall and its instantaneous angular velocity is ω. Let us introduce the speed $v' = r\omega$: when v' reaches the instantaneous speed v, it no longer changes (see Solution #1 for explanation). The equation for the rotational motion of the puck is (see Solution #1 for explanation)

$$r\frac{d\omega}{dt} = \frac{dv'}{dt} = \frac{\mu m r^2}{RI}v^2.$$

Having already written the function $v(\varphi)$ (6), we also want to write v' as a function of φ. We start with the relation

$$\frac{dv'}{dt} = \frac{dv'}{d\varphi}\frac{d\varphi}{dt}$$

and with the use of $d\varphi/dt = v/R$ we get

$$dv' = 2\mu v_0 \exp(-\mu\varphi)d\varphi$$

and solving a simple integral

$$\int_0^{v'} dv' = 2\mu v_0 \int_0^{\varphi} \exp(-\mu\varphi)d\varphi$$

we get

$$v'(\varphi) = r\omega(\varphi) = 2v_0(1 - \exp(-\mu\varphi)). \qquad (7)$$

If we equate v and v', we get a critical angle φ_c at which rolling with sliding changes to rolling without sliding,

$$\mu\varphi_c = \ln\frac{3}{2}.$$

At the critical angle, the final velocity is $v_f = v_0 \exp(-\mu\varphi_c) = 2v_0/3$.

If $\varphi_c > \pi$ i.e. $\mu\pi < \ln\frac{3}{2}$, the puck still slides at the exit with the exit speed $v_e = v_0 \exp(-\mu\pi)$ and if $\varphi_c \leq \pi$ i.e. $\mu\pi \geq \ln\frac{3}{2}$, the puck rolls at the exit without sliding with the final speed $v_e = v_f = v(\varphi_c) = 2v_0/3$.

From the way the problem is solved in the second solution, it can be seen that the exit speed of the puck does not depend on a particular shape of the wall; the speed and the angular velocity depend only on φ (and the friction coefficient μ). For example, the wall could be elliptical instead of a semicircle (or have a different shape).

suggestions for marking scheme

Part T1.a): Scores	Pts.
realizing that puck is sliding initially	0.3
realizing that puck may roll without sliding	0.3
stating that sliding ends when roll condition $v = r\omega$ is met	0.3
equating the normal force with mv^2/R	0.3
using $F_f = \mu N$ for the friction force	0.3
equation of motion (eom) for translation (-0.2 for wrong sign)	0.4
giving integral expression for translational eom with correct initial conditions	0.5
giving expression for v as function of time or angle as in eq. (2) or (6)	1.0
equation of motion (eom) for rotation	0.4
using $I = mr^2/2$ as moment of inertia	0.3
giving integral expression for rotational eom with correct initial conditions	0.5
giving expression for $r\omega$ as function of time or angle as in eq. (3) or (7)	1.0
getting time $\frac{R}{2v_0\mu}$ or angle $\ln(\frac{3}{2})/\mu$ for transition to rolling without sliding	0.5
obtaining critical coefficient of friction $\mu_c = \ln(3/2)/\pi$	0.5
finding final velocity $\frac{2}{3}v_0$ for rolling without sliding	0.4
finding velocity v_e if puck slides the whole time	1.0
Total on T1.a)	**8.0**

Part T1.b): Scores	Pts.
graph has suitably labelled axis	0.2
initial speed v_0 indicated in graph	0.2
graph shows v_e decreasing with μ initially	0.3
initial exponential decrease of v_e with μ indicated in graph	0.3
critical point exists and is indicated in graph	0.4
constant speed after the critical point	0.4
obviously not smooth function at critical point	0.2
Total on T1.b)	**2.0**

General rules for marking in T1:

- The grain size for marking is 0.1 Pts.
- Partial marks can be awarded for most aspects.
- For each mistake in calculation (algebraic or numeric) 0.2 Pts. are deducted.
- If a mistake leads to a dimensionally incorrect expression no marks are given for the result.
- Propagating errors are not punished again unless they are dimensionally wrong or entail oversimplified/wrong physics (e.g. neglecting friction effects).

T2: Spaceships - Solution

Analytical Solutions

Let us denote the reference frames of Alice, Bob and gift by A, B, G, respectively. We shall use the notation $\gamma_v = \frac{1}{\sqrt{1-v^2/c^2}}$.

Part a) (i)

Solution 1: Let l_x be the distance between two gifts in frame x. Since G is the rest frame of the gifts, we have $l_A = l_G/\gamma_v$, $l_B = l_G/\gamma_{v_B}$, where v_B is the relative velocity of frames B and G. According to the formula for relativistic addition of velocities, the relative velocity v_B is given by

$$v_B = \frac{u+v}{1+uv/c^2} = \frac{35}{37}c, \tag{8}$$

where we used the values $u = \frac{3}{5}c, v = \frac{4}{5}c$. Together with $l_A = v\Delta t_0$ this gives

$$l_B = v\Delta t_0 \frac{\gamma_v}{\gamma_{v_B}} = \frac{16}{37}\Delta t_0 c.$$
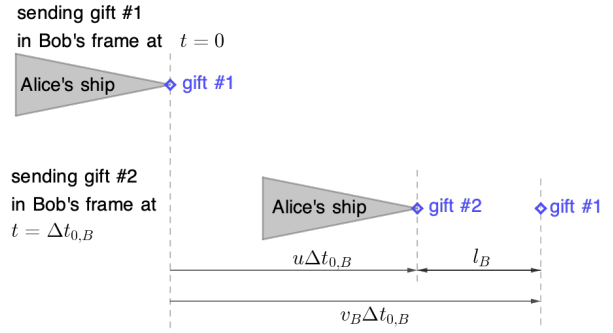
Solution 2: Let us consider the two events that gift 1 is sent and the consecutive gift 2 is sent. According to Lorentz-transformation, if an event has coordinates t, x in a certain reference frame, the same event has coordinates $t' = (t - ux/c^2)\gamma_u, x' = (x - ut)\gamma_u$, where u is the relative velocity of the reference frames. In A, these events have coordinates $(t_{1,A}, x_{1,A}) = (0,0)$ and $(t_{2,A}, x_{2,A}) = (\Delta t_0, 0)$. The relative velocity of A and B is $-u$. Therefore, in B these events have coordinates $(t_{1,B}, x_{1,B}) = (0,0)$ and $(t_{2,B}, x_{2,B}) = (\tau\gamma_u, u\Delta t_0\gamma_u)$.

We thus need to determine the position of gift 1 at time $t_{2,B}$ in frame B. If v_B is the relative velocity of the gift and B given by (8), the position of gift 1 is given by $x_{1,B}(t_{2,B}) = v_B t_{2,B}$. Hence, in frame B the distance between the two gifts is

$$l_B = x_{1,B}(t_{2,B}) - x_{2,B}(t_{2,B}) = (v_B - u)\Delta t_0 \gamma_u = \frac{16}{37}\Delta t_0 c.$$

Solution 3: The time interval $\Delta t_0 = \Delta t_{0,A}$ is the proper time of events in Alice's frame (Alice sending gifts, which happen at the same location in Alice's frame), which is moving with u in Bob's frame. Time interval between these events in Bob's frame is $\Delta t_{0,B} = \gamma_u \Delta t_{0,A}$. The speed of the gift Alice sent in Alice's frame is $v_A = v = \frac{4}{5}c$ and in Bob's frame the speed of the gift is v_B as found in (8). In Bob's frame in the time interval $\Delta t_{0,B}$ two gifts are sent. During this time the Alice's ship has moved for $u\Delta t_{0,B}$, the previously sent gift for $v_B\Delta t_{0,B}$ and the distance between both gifts in Bob's frame is

$$l_B = (v_B - u)\Delta t_{0,B} = \frac{16}{37}c\Delta t_0.$$

sending gift #1
in Bob's frame at $t = 0$

Alice's ship ◇ gift #1

sending gift #2
in Bob's frame at $t = \Delta t_{0,B}$

Alice's ship ◇ gift #2 ◇ gift #1

$u\Delta t_{0,B}$ l_B

$v_B\Delta t_{0,B}$

Solution 4: If a student solves Part (ii) first, then the distance between two of the gifts from Bob in Alice's reference frame is the product of the time between arrival, Δt_1, and the speed of Bob's gift in Alice's frame, which is found from the relativistic velocity addition in Eq. 8. Then

$$l_B = v_B\Delta t_1 = \left(\frac{35}{37}\right)c\left(\frac{16}{35}\right)\Delta t_0 = \frac{16}{37}c\Delta t_0$$

Part a) (ii)

Solution 1 Assuming that the Part (i) is solved first

The time interval is given by

$$\Delta t_1 = \frac{l_B}{v_B} = \frac{16}{35}\Delta t_0$$

Problem 2.(a): Using Solution 1	pts
Formula for relativistic addition of velocities each mistake -0.3	0.5
Speed v_B of Alice's gift in B ($35/37 = 0.\overline{945}$) must have correct formula	0.5
Find l_A	0.5
γ formula each mistake -0.2	0.3
$l_1 = l_2/\gamma$ only true in rest frame	0.7
Boost l_A to G frame each mistake -0.1	0.3
Boost from G frame to l_B each mistake -0.1	0.2
Collect expressions for l_B	0.5
correct numerical result ($16/37 = 0.\overline{432}$) must have correct formula	0.5
$\Delta t_1 = l_B/v_B$	0.5
correct numerical result ($16/35 \approx 0.457$) must have correct formula	0.5
Total for 2.(a)	**5.0**

Problem 2.(a): Using Solution 2 or 3	pts
Formula for relativistic addition of velocities each mistake -0.3	0.5
Speed v_B of Alice's gift in B ($35/37 = 0.9\overline{45}$) must have correct formula	0.5
γ formula each mistake -0.2	0.3
because two subsequent gifts are sent from the same place in Alice's frame	0.7
$\Delta t_{0,B} = \gamma_u \Delta t_0$ each mistake -0.1	0.3
In Bob's frame, second gift at position $u\Delta t_{0,B}$ while first gift at $v_B \Delta t_{0,B}$ each mistake -0.2	0.7
Collect expressions for l_B	0.5
correct numerical result ($16/37 = 0.\overline{432}$) must have correct formula	0.5
$\Delta t_1 = l_B/v_B$	0.5
correct numerical result ($16/35 \approx 0.457$) must have correct formula	0.5
Total for 2.(a)	**5.0**

Important Notes for marking Problem 2

- Correct final answers without justification can receive full marks; incorrect final answers without justification will receive no marks, even if the answer is "close" or if it can be guessed what the error was.
- The statement "must have correct formula" means that the any immediately preceeding symbolic formula to the numerical number must be correct to receive any points for a numerical answer.
- Correct numerical result is dependent only on the immediate formula from which it is computed.
- A dimensionally incorrect formula gets zero marks.
- Student can define $c = 1$ explicitly without penalty, but inconsistencies are treated as errors.
- Follow on errors normally only have penalty at point of error
- Numerical results that are follow on errors are not penalized twice
- must have recognized light time correction need at least once to get points for ratio formula AND result
- Transcription errors are errors
- If Part a) is solved without the explicit use of special relativity, then the maximum possible for part a) is 0.5 pts.
- If Part b) is solved without the explicit use of special relativity, then no points are awarded.
- For final answer on Part b), must have correct formula; non integer numbers that round to 18 get only +0.2 pts.
- Any other mistakes or errors not explicity covered in the marking schemes should be treated a fully wrong for the category; so if a category is listed as 0.6, and the student work is incorrect, and no other disclaimer applies, then the score would be 0.
- If a student could only reasonably have correctly completed some task by correctly doing the previous tasks, then the previous tasks should be fully

awarded, even if not explicitly written. However, if the tasks are written, and have errors, the student will get the appropriate deductions.
- If it can be argued that a student could only reasonably have completed some task by correctly doing the previous tasks, but the answer to the shown task is incorrect, then the previous tasks should receive zero marks if not explicitly shown.

Part (b)

Solution 1: Suppose that at $t_{0,A} = 0$ Alice sees Bob's spaceship at distance d_B. The time that the light travelled from Bob to Alice is $t_l = d_b/c$. (In Alice's frame, the actual distance from Alice to Bob's spaceship is $L = d_b - ud_b/c$.)

Let us first compute the number of visible outgoing gifts. Alice sees all gifts she sent until she sees them reach the spaceship. Consider the gift which Alice just sees arriving at Bob, which is the oldest visible gift. If this gift flew past Bob's ship, it would be located at distance $d_b + vt_l$. Therefore the number of gifts between the oldest visible gift and Alice is

$$N_{out} = \frac{d_b + vt_l}{l_A} = \frac{d_b(1 + v/c)}{v\Delta t_0}.$$

Alternatively, one can observe that d_b/l_A gifts were between the considered gift and Alice at time $-t_l$. During time t_l Alice sent out an additional number $t_l/\Delta t_0$ gifts, giving $N_{out} = \frac{d_B}{v\Delta t_0} + \frac{d_B}{c\Delta t_0}$.

We now compute the number of visible incoming gifts. Alice sees the newest visible gift just leave Bob's ship. In Alice's frame, the actual distance of her to the newest visible gift is $d_b - v_B t_l = d(1 - v_B/c)$. The distance between incoming gifts is l_B, which was computed in part a). Hence, the number of visible incoming gifts is

$$N_{in} = \frac{d_B(1 - v_B/c)}{l_B} = \frac{d_B(1 - v_B/c)}{\Delta t_0 c}\frac{37}{16}$$

In total, we have

$$\frac{N_{out}}{N_{in}} = \frac{(1 + v/c)c}{(1 - v_B/c)v}\frac{16}{37} = 18$$

Solution 2 Since both Alice and Bob send the gifts in exactly the same way and their relative speed to each other is also the same (which is always the case), there is symmetry between them. Bob sees exactly the same number of gifts he will receive as Alice, and the same is true for the gifts sent. So we can continue in Bob's frame (where Bob is stationary).

First, let us look at the gifts Bob receives (and we stay in his frame the whole time). Between Bob and Alice at any moment, there are a finite number of gifts that have already been sent by Alice and not yet received by Bob. However, Bob does not see them all because the light of the most distant gift has not yet reached him. The furthest gift #A that Bob can see was sent to him at time $t = 0$ (in Bob's frame) and Bob sees it for the first time at time t_1, when it has already

traveled the distance $v_B t_1$ and the light of this gift, emitted at time $t = 0$ (when it was sent) has traveled the distance $c t_1$ and has just reached him (at time t_1 Bob sees the gift #A sent from Alice's position at time $t = 0$). The distance between two consecutive gifts moving towards Bob is $v_B \Delta t_1$ (see part (ii), solution 1). The number of gifts that Bob sees at any point in time and that move towards Bob is

$$N_{A \to B} = \frac{(c - v_B) t_1}{v_B \Delta t_1}. \tag{9}$$

gift #A was sent in Bob's frame at $t = 0$
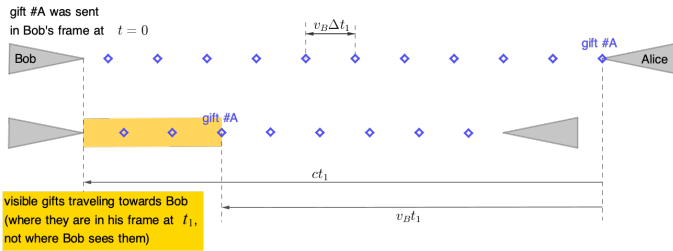
Let us now turn to the gifts that Bob sends to Alice. Bob sees all his gifts that have not yet reached Alice at the time of observation, and some more that have been with Alice for some time and are probably eaten – only the information about the receipt of the gifts has not yet reached Bob. Let the moment $t = 0$ be the moment at which the gift #B sent by Bob reaches Alice. At this moment, the light from Alice begins to travel back to Bob with the information about the receipt of the gift and reaches Bob at time t_1 – then Bob realizes that the gift #B has been received. Between $t = 0$ and t_1, Bob regularly sends more gifts in the usual way; therefore, there are more gifts that Bob can see on the way to Alice than there actually are (remember: we are always talking about how things are in Bob's frame; when and where they happen). It's practically the same as the received gift #B moves further beyond Alice and travels an additional distance $v t_1$ before Bob realizes it's being received by Alice. The number of gifts that Bob sees at any point in time and that move away from Bob is

$$N_{B \to A} = \frac{(c + v) t_1}{v \Delta t_0}. \tag{10}$$

gift #B was received in Bob's frame at $t = 0$
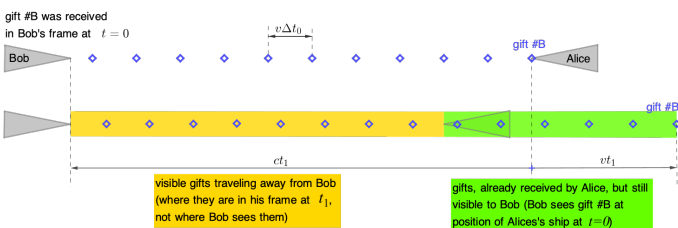
The gift #A is sent by Alice to Bob at time $t = 0$ and at the same moment Alice receives the gift #B from Bob (same time and place), and Bob observes travelling gifts at time t_1.

The ratio of the number of gifts moving away from him and towards him is

$$\frac{N_{B \to A}}{N_{A \to B}} = \frac{(c + v) t_1}{v \Delta t_0} \frac{v_B \Delta t_1}{(c - v_B) t_1} = \frac{(c + v) v_B \Delta t_1}{v \Delta t_0 (c - v)} = 18, \tag{11}$$

where the previously obtained relationships $\Delta t_1 = \frac{16}{35} \Delta t_0$ and $v_B = \frac{35}{37} c$ were used together with the given $v = \frac{4}{5} c$.

Problem 2.(b)	pts
Identify a distance to Bob d_B	0.3
Light time to Bob t_l	0.5
Recognize need to correct for light time	0.5
$d_{AG} = d_B + t_l v$ each mistake -0.3	0.9
$N_{a \to b} = d_{AG}/L_A$	0.2
Recognize need to correct for light time	0.5
$d_{BG} = d_B - t_l v_B$ each mistake -0.3	0.9
$N_{b \to a} = d_{BG}/L_B$	0.2
symbolic ratio each mistake -0.2	0.5
correct numerical result (18) must have correct formula	0.5
Total for 2.(b)	**5.0**

Graphical Solutions

Throughout the graphical solution, it is assumed that $c = 1$ and $\Delta t_0 = 1$. In order to return to a consistent solution, make sure to include these factors appropriately in the final answer.

Part a)i

The question is asking for the separation between two events that happen at the same *time* in Bob's reference frame. The graph is in Alice's reference frame, also shown in the graph are the world line of Bob, with a slope of $-5/3$, and the x-axis of Bob, with a slope of $-3/5$. The red circle on Alice's world line is the launch of a gift from Alice, the black circle at the origin is another launch of a gift from Alice.
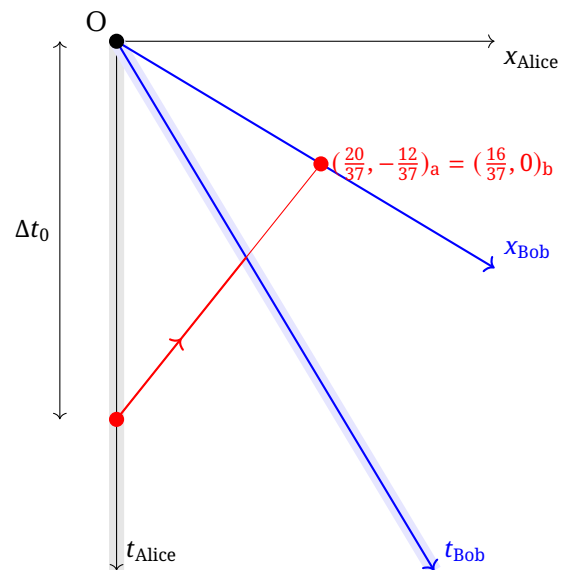
We are interested in the intersection of the first launched gift, which has a slope of $5/4$, where it crosses the x axis of Bob. In Alice's reference frame, that point is

$$(x, t) = \left(\frac{20}{37}, \frac{-12}{37} \right)$$

Applying the Lorentz transform into Bob's reference frame,

$$\Delta t_1 = \frac{5}{4}\left|\frac{20}{37} - \left(\frac{-3}{5}\right)\left(\frac{-12}{37}\right)\right| = \frac{16}{37}$$

Alternatively, it is possible to focus on the Lorentz invariant expression,

$$(t_a)^2 - (x_a)^2 = (t_b)^2 - (x_b)^2$$

where $t_b = 0$, and arrive at the same result.

Part a)ii

It is expected that most students will get an answer that depends on the result of Part a)i, and the technique is outlined in the analytical section.

It is also possible to solve Part a)ii without solving Part a)i. Consider world-lines for Alice and Bob that intersect at the origin, and assume that both send a gift to the other at this intersection.
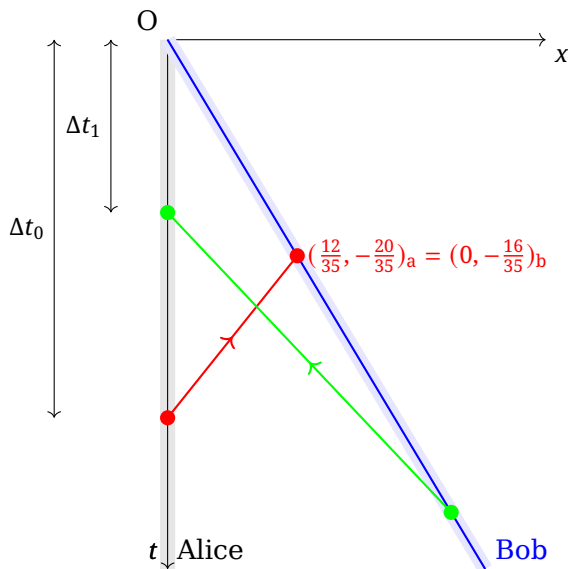
The question is asking for the time interval between two events that happen in the same place in Bob's reference frame.

The world-line of Bob has a slope of -5/3; the world-line of the gift from Alice has a slope of 5/4. Assuming $\Delta t_0 = 1$, then the gift from Alice arrives with Bob in Alice's coordinate system as

$$(x, t) = \left(\frac{12}{35}, \frac{-20}{35}\right)$$

Applying the Lorentz transform into Bob's reference frame,

$$\Delta t_1 = \frac{5}{4}\left|\frac{-20}{35} - \left(\frac{-3}{5}\right)\left(\frac{12}{35}\right)\right| = \frac{16}{35}$$

Alternatively, it is possible to focus on the Lorentz invariant expression,

$$(t_a)^2 - (x_a)^2 = (t_b)^2 - (x_b)^2$$

where $x_b = 0$, and arrive at the same result.

Because of the symmetry, the time interval between arrivals of Bob's gift in Alice's frame is the same as the time interval between arrivals of Alice's gift in Bob's frame. The transfer of the gifts in shown in the figure. It is not necessary to sketch this green line.

Problem 2.(a)i	pts
Clearly indicated graph or related equations	0.2
Bob's x axis correct slope (-3/5)	0.2
Gift from Alice correct slope (5/4)	0.2
Gift released Δt_0 before Origin	0.2
Recognize intersection of gift and x_B	0.3
Find intersection in Alice Frame	0.5
1. γ formula	0.3
1. each mistake -0.2	
1. Use Lorentz Transformation	0.1
1. Apply Lorentz Transformation	0.5
1. each mistake -0.2	
2. Use Lorentz invariance	0.4
2. recognize $\Delta x_b = 0$	0.2
2. Apply Lorentz invariance	0.3
2. each mistake -0.2	
correct numerical result (16/37)	0.5

Important Notes!

1. Scores can be received for method 1 or method 2, but not both; if both are attempted, award the higher total, but never more than 0.9 pts.

If Part a)ii is solved analytically

Problem 2.(a)ii	pts
Formula for $v_{addition}$ each mistake -0.3	0.5
Speed v_r of Alice's gift in B (35/37) must have correct formula	0.5
$\Delta t_1 = L_b / v_r$	0.5
correct numerical result (16/35) must have correct formula	0.5

If Part a)ii solved graphically, then

| Problem 2.(a)ii	pts
Clearly indicated graph or related equations	*0.2
Bob's t axis correct slope (-5/3)	0.2
Gift from Alice correct slope (5/4)	*0.2
Gift released Δt_0 before Origin	*0.2
Recognize intersection of gift and t_B	0.3
Find intersection in Alice Frame	0.5
1. γ formula	*0.3
1. each mistake -0.2	
1. Use Lorentz Transformation	*0.1
1. Apply Lorentz Tranformation	0.5
1. each mistake -0.2	
2. Use Lorentz invariance	*0.4
2. recognize $\Delta x_b = 0$	0.2
2. Apply Lorentz invariance	0.3
2. each mistake -0.2	
correct numerical result (16/35)	0.5

Important Notes!

1. A student who does both a)i and a)ii graphically can only get points for the starred (*) categories

for the work in a)i, and not also for the work in a)ii.

2. The maximum possible score is 5 pts! If a student does graphical approaches for both, and makes mistakes, the final score for Part a) must be less than 5 by an amount equal to the mistakes made.

Part b)

Consider the movement of gifts in Alice's reference frame. Green gifts are headed toward Alice, red gifts are headed away from Alice. If Alice makes an instantaneous observation, Alice will see the gifts at locations along the intersection with the diagonal light line. This is quite different from the questions of the separation of the green gifts or the red gifts in Alice's rest frame, which is measured by the separation at the same time, for example, the intersections with the x axis.
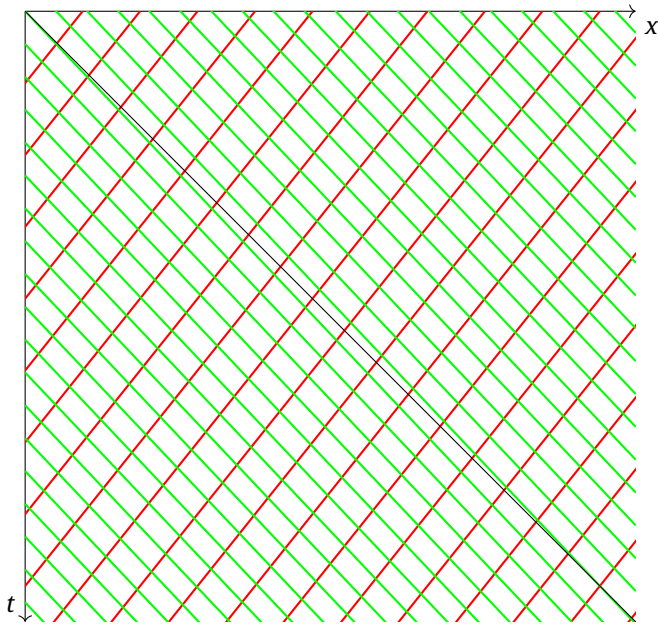
The figure to solve can be simplified considerably; to fit it into a useful form the proper slopes are no longer used and the picture is not to scale.
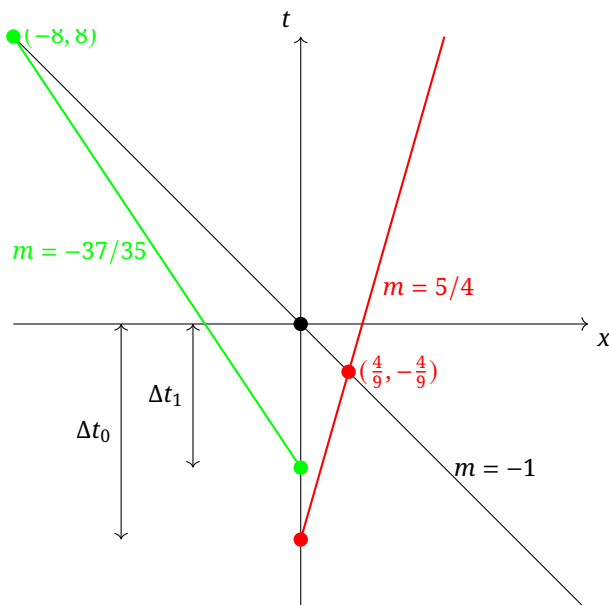
The intersection of the red line and the black light-line is

$$\left(\frac{4}{9}, -\frac{4}{9}\right)$$

The intersection of the green line and the black light line is

$$(-8, 8)$$

The ratio is 18.

| Problem 2.(b)	pts
Clearly indicated graph or related equations	0.4
Alice's gifts correct slope (5/4)	0.2
Formula for $v_{addition}$ each mistake -0.3	*0.5
Speed v_r of Bob's gift in A (35/37) must have correct formula	*0.5
Bob's gifts correct slope (-37/35)	0.2
Light-like line drawn	0.2
Alice gift released Δt_0 before Origin	0.2
Bob gift arrive Δt_1 before Origin	0.2
Intersection of Bob gift and light like line	0.3
Find intersection in Alice Frame	0.5
Intersection of Alice gift and light like line	0.3
Find intersection in Alice Frame	0.5
symbolic ratio each mistake -0.2	0.5
correct numerical result (18) must have correct formula	0.5

Important Notes for marking Problem 2 b)

1. For the two starred (*) quantities above: If this is the first use of the relativistic velocity addition formula, then mark as shown. If the relativistic velocity addition was was used to answer Part a), then these points are only awarded for a student who has reasonably demonstrated how they need to use the relative velocity to solve Part b). An appropriate figure can be sufficient. In this case, they do not need to write the equations twice.

Solution using ict-diagrams

In the ict-diagram shown in the figure, the red coordinate system represents the Bob's frame of reference, the blue represents the Alice's frame, and the black represents the gifts' frame. We know that $\tan\alpha = \frac{v}{ic} = -\frac{3}{5}i$ and $\tan\beta = \frac{u}{ic} = -\frac{4}{5}i$. Therefore,

$$\tan\gamma = \tan(\alpha+\beta) = \frac{\tan\alpha + \tan\beta}{1 - \tan\alpha\tan\beta} = -\frac{140}{148}i.$$

We can express sinus and cosine in terms of tangent to obtain $\cos\alpha = \frac{5}{4}$, $\sin\alpha = -\frac{3}{4}i$, $\cos\beta = \frac{5}{3}$, $\sin\beta = -\frac{4}{3}i$, $\cos\gamma = \frac{37}{12}$, $\sin\gamma = -\frac{35}{12}i$. Events A and B represent the launching of two consecutive gifts, so the segment AB is of length $ic\tau$.
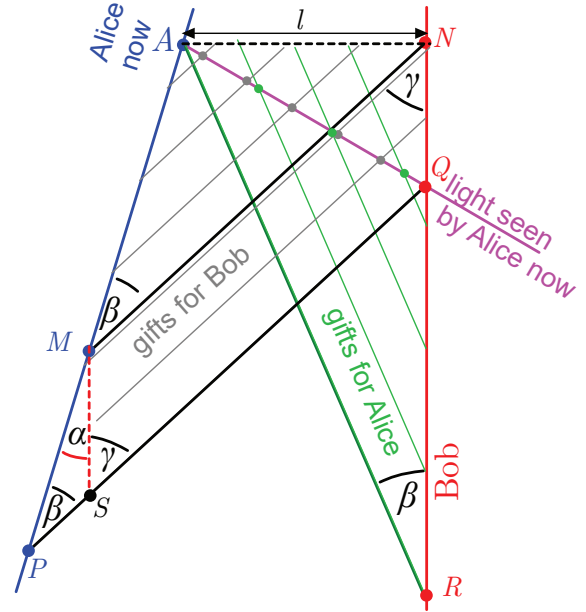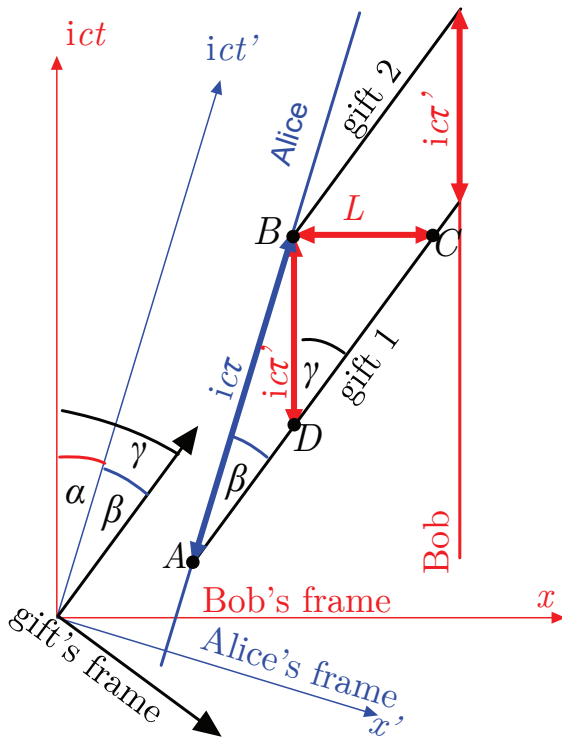
Part a)1 The distance between two gifts launched by Alice in the Bob's frame of reference is labeled L in the figure. From the sine theorem for the triangle ABC we obtain $L = \mathrm{i}c\tau \sin\beta/\cos\gamma = \tau c \frac{4}{3}\frac{12}{37} = \frac{16}{37}c\tau$.

Part a)2 From the sine theorem for the triangle ABD we obtain $\tau' = \tau \sin\beta/\sin\gamma = \tau\frac{4}{3}\frac{12}{35} = \frac{16}{35}c\tau$.

Part b) We use the same reference frames and a diagram using the same color-coding. Additionally, the diagram shows the gifts sent by Bob in green, and the light ray arriving currently to Alice's eye in purple. The gifts seen by Alice are marked as coloured circles: the ones sent by herself are grey, and the ones sent by Bob are green. Since the gits are launched by Bob and Alice at the same frequency, the ratio of the number of grey gifts to the number of green gifts seen currently is equal to AP/RQ.

From the figure we can easily express $AP = AM+NP$; using the sine for the triangle AMN theorem we obtain $AM = l\cos\gamma/\sin\beta = \frac{37}{16}\mathrm{i}l$; here, l denotes the distance to Alice now in Bob's frame of reference. Since light travels with speed c, we know that $QN = \mathrm{i}L$; the sine theorem for the triangle MPS yields $MP = MS \sin\gamma/\sin\beta = QN \sin\gamma/\sin\beta = \mathrm{i}\frac{35}{16}l$ so that $AP = \mathrm{i}\frac{72}{16}l = \mathrm{i}\frac{9}{2}l$. One can easily see that $RQ = RN - QN = l/\tan\beta - \mathrm{i}l = \mathrm{i}\frac{1}{4}l$. Bringing all together, the ratio of the number of gifts is $AP/RQ = \frac{9}{2}\frac{4}{1} = 18$.

T3: Fabry–Pérot interferometer - Solution

Throughout these solutions, we use a Cartesian coordinate system aligned so that the x axis points along the normal to the mirrors. Let one mirror be positioned at $x = 0$ and the other at $x = L$, and suppose the beam approaches the interferometer from the negative-x direction. Let regions I, II and III be defined by $x < 0$, $0 < x < L$ and $x < L$ respectively. Note that the mirrors are assumed thin for convenience here, but this does not change the answers.

Solution 1

Part a Where the laser beam meets the first mirror of the interferometer, some light is reflected back towards the laser and the rest is transmitted into the space between the mirrors (region II). This transmitted light bounces back and forth between the mirrors. With every reflection, some light is transmitted and leaves the interferometer. To find the complex amplitude of the wave returning to the laser, we need to sum the complex amplitudes of the wave that reflects immediately (without ever entering the interferometer), as well as those of the waves that bounced back and forth once, twice, thrice, etc.

Each region therefore contains a superposition of infinitely many waves. Crucially, a superposition of any number of sinusoidal waves with the same frequency, wavelength and propagation direction can be represented by a single sinusoidal wave with the same frequency, wavelength and propagation direction. Therefore, the electric field due to the waves in regions I, II and III must take the following form.

Region I: $\quad E(x,t) = A\,e^{i(kx-\omega t)}$,

Region II: $\quad E(x,t) = B\,e^{i(kx-\omega t)} + C\,e^{i(-kx-\omega t)}$,

Region III: $\quad E(x,t) = D\,e^{i(kx-\omega t)}$.

In region I, we have a travelling wave moving in the positive x direction with wavenumber k, angular frequency ω and amplitude A. The condition that there is no back-reflected beam means there is no oppositely-propagating wave in region I. In region II, the electric field is a sum of two waves propagating in either direction, which we give complex amplitudes B and C. Finally, in region III, there is only a wave propagating in the positive-x direction, which we give complex amplitude D.

Let us introduce an amplitude reflection coefficient r and transmission coefficient t for the mirrors. These coefficients, which may be complex, are characteristic of the mirrors. The ratio between the complex amplitude of the reflected wave and the incident wave is r, while the ratio between the complex amplitude of the transmitted wave and the incident wave is t. We are interested in ϕ, which is the relative phase between the complex numbers r and t.

Let us work out how the waves on either side of the first mirror (in regions I and II) are related. In region II, the forward-propagating wave is a result of

the transmitted part of the incident wave in region I, and the reflected part of the backwards-propagating wave in region II. Therefore,

$$B = tA + rC \ . \tag{12}$$

Similarly, for the backwards-propagating wave in region I to vanish, the sum of the reflected part of the incident wave and the transmitted part of the backwards-propagating wave in region II must be zero:

$$0 = rA + tC \ . \tag{13}$$

Furthermore, applying similar reasoning at the second mirror, using the complex amplitudes evaluated at $x = L$, leads to

$$D\,e^{ikL} = tB\,e^{ikL} \ , \tag{14}$$

$$C\,e^{-ikL} = rB\,e^{ikL} \ . \tag{15}$$

If r and t are given, along with the amplitude of the initial wave A, equations (12)–(15) contain four unknowns: B, C, D and k. We find

$$e^{-2ikL} = r^2 - t^2 \ . \tag{16}$$

This relation tell us the argument of the complex number $r^2 - t^2$; it must be $-2kL$. It also provides a constraint on the magnitude of this complex number; we must have

$$|r^2 - t^2| = 1 \ . \tag{17}$$

This is a condition that r and t must satisfy in order for the setup in the question, with no back-reflected light from the interferometer, to be realizable.

With lossless mirrors, there is one additional constraint that r and t must satisfy. When a wave passes through one of these mirrors, the incident power must equal the sum of the reflected and transmitted powers. Since every wave in the problem has the same speed, the power carried by them is proportional the their amplitude squared, which means it is proportional to the modulus squared of the complex amplitude. Therefore, conservation of energy requires

$$|r|^2 + |t|^2 = 1 \ . \tag{18}$$

Together, (17) and (18) imply that r and t cannot both be real; there must be some phase shift between the transmitted and reflected light.

Part b Using conditions (17) and (18), we can show that the magnitude of ϕ is $90°$. Here are two ways we could do this.

First, we could square both conditions and subtract:

$$|r^2 - t^2|^2 = |r|^4 + |t|^4 - r^2 t^{*2} - r^{*2} t^2 = 1$$
$$(|r|^2 + |t|^2)^2 = |r|^4 + |t|^4 - r|r|^2|t|^2 = 1$$
$$\implies 2|r|^2|t|^2 = r^2 t^{*2} + r^{*2} t^2 \ .$$

Here, an asterisk denotes complex conjugation. This is equivalent to $(rt^* + r^*t)^2 = 1$ or

$$\frac{r}{t} + \frac{r^*}{t^*} = 0 \ .$$

This says that r/t is purely imaginary, so r and t must have arguments that differ by $\pm 90°$.

Alternatively, we could let $a = r^2$ and $b = t^2$, so that (17) and (18) read

$$|a - b| = 1$$
$$|a| + |b| = 1 \ .$$

Using O to denote the origin and A and B, respectively, to denote the points a and b in the complex plane, consider the triangle OAB. The first condition above implies that the length of side AB is 1. The second implies that the sum of the lengths OA and OB is also 1. Thus, the points O, A and B must actually be collinear, with O in between A and B. So, b and a have arguments that differ by $180°$. Since a and b have twice the arguments of r and t (respectively), this means r and t must have arguments that differ by $\pm 90°$.

Part c When the laser is rapidly switched off, after the amount of time it takes light to travel from the laser to the first mirror, the incident wave will be removed.

Since $|t| \ll |r|$, the amplitudes $|B|$ and $|C|$ are very large. Furthermore, the difference between them is small. Physically, the interferometer contains a large amount of electromagnetic energy in two waves of roughly equal intensity, propagating in either direction. This means, when this stored energy is released from the interferometer, the release will be very nearly symmetrical. Approximately the same amount of energy will be released in either direction. So, the energy contained in the pulse that propagates towards the laser is must be about half of the stored initial energy.

To find the stored energy, suppose the power contained in each wave (forwards- and backwards-propagating) in region II is P'. The power transmitting through the mirrors to leave the interferometer is $(1 - R)P'$. Since this transmitted wave must perfectly cancel out the wave that reflects from the first mirror, which has power $Rp \approx P$, we must have $P' \approx P/(1 - R)$. This means the initial energy stored inside the interferometer is

$$U \approx \frac{2}{1 - R} \frac{LP}{c} \ ,$$

since the energy of the two waves travelling in either direction simply adds. Therefore, the energy in the pulse that returns to the laser is

$$E \approx \frac{1}{1 - R} \frac{LP}{c} \ .$$

Part d There are at least two ways of doing this part; see Solution 2 below for a second approach.

The stored energy is initially given by (19). The Poynting flux out of the interferometer at the moment when the incoming beam has just switched off all the way to the surface of the first mirror is roughly

$$\frac{dU}{dt} = -2P = -\frac{(1 - R)c}{L} U \ , \tag{19}$$

since the amplitudes of the waves propagating away from the interferometer in regions I and III are both roughly $|A|$. We can assume that the stored energy decays exponentially: if the field inside the device reduces by a certain factor, then the amplitude of the waves just outside will have reduced by the same factor. So, the ratio between the stored energy inside and the outwards Poynting flux is roughly constant. Finding the time constant T so that $U \propto e^{-t/T}$ satisfies (19) leads to

$$T \approx \frac{1}{1 - R} \frac{L}{c} \ .$$

Since this is an estimate, and since the exact numerical prefactor depends on whether we chose to use the time constant for the decay in amplitude or energy, students can have any order-unity prefactor. Since the combination L/c can be deduced by dimensional analysis, the marks should be awarded for getting the correct dependence on R on.

Solution 2

Part a It is possible to solve this problem by summing up an infinite series of complex amplitudes corresponding to the light waves that are reflected once, twice, thrice, etc. from the mirror.

Let us focus on the backwards-propagating wave in region I, which must vanish. In steady state, before the laser is switched off, let the amplitude of the incident beam at $x = 0$ be A. Then, introducing amplitude reflection coefficients r and t as in Solution #1, the amplitude of the backwards-propagating beam is

$$rA[1 + t^2(e^{2ikL} + r^2 e^{4ikL} + r^4 e^{6ikL} + \ldots)] \ .$$

The first term represents the light that is reflected immediately off the first mirror (factor r, without every entering region II. The remaining terms represent light that transmits through the first mirror (one factor t), propagates from $x = 0$ to $x = L$ and back some number N of times (factor e^{2NikL} due to the propagation and r^{2N-1} for the correct number of reflections) and transmits through the first mirror again (second factor of t. Summing the geometric series, the backwards-propagating amplitude is

$$rA \left(1 + \frac{t^2 e^{2ikL}}{1 - r^2 e^{2ikL}} \right) = 0 \ .$$

Rearranging leads to the same condition (16) as in Solution #1. The rest of the solution, to conclude that r and t meet at a right angle and that t must have a nonzero phase, can proceed as in Solution #1.

Part b As in Solution #1.

Part c After the incident beam has switched off all the way to the interferometer, the beam the is reflected immediately off the first mirror switches off. The other beams, corresponding to light that bounces some number N of times between the mirrors, switches off slightly later. So, the backwards-reflected beam at first becomes

$$rA[t^2(e^{2ikL} + r^2 e^{4ikL} + r^4 e^{6ikL} + \ldots)] = -rA \ .$$

At $x = 0$, this is the amplitude of the backwards-reflected beam for time $\Delta t = 2L/c$.

Then, the wave that reflects once before leaving also switches off, after time Δt. The amplitude becomes

$$rA[t^2(r^2\mathrm{e}^{4ikL} + r^4\mathrm{e}^{6ikL} + \ldots)] = rA\,\frac{t^2 r^2 \mathrm{e}^{4ikL}}{1 - r^2 \mathrm{e}^{2ikL}} = rAr^2\,\mathrm{e}^{2ikL}$$

for the next Δt. Then, the wave that is reflected three times before leaving switches off, after time $2\Delta t$. The amplitude becomes

$$rA[t^2(r^4\mathrm{e}^{6ikL} + \ldots)] = rA\,\frac{t^2 r^4 \mathrm{e}^{6ikL}}{1 - r^2 \mathrm{e}^{2ikL}} = rAr^4\,\mathrm{e}^{4ikL} \ ,$$

and so on. After time $n\Delta t$, the amplitude is $-rAr^{2n}\mathrm{e}^{2nikL}$. The modulus decreases by a factor of R every Δt. This can be argued without a geometric series; each wave has reflected two more times that the previous one, so should have an amplitude that is a factor of R smaller.

The energy in the backwards-propagating pulse is the sum of the energies during the first, second, third, etc Δt interval. This is

$$P\Delta t(|r|^2 + |r|^6 + |r|^8 + \ldots) = \frac{|r|^2}{1 - |r|^4}\,\frac{2LP}{c} \approx \frac{1}{1 - R}\,\frac{LP}{c} \ .$$

Part d   Since the amplitude decays like

$$R^n = \mathrm{e}^{-n\log 1/R} = \mathrm{e}^{-\log(1/R)t/\Delta t} \ ,$$

the energy decays like $\mathrm{e}^{-2\log(1/R)t/\Delta t}$. The time constant of this roughly-exponential decay in energy is

$$T = \frac{\Delta t}{2\log(1/R)} \approx \frac{1}{1 - R}\,\frac{L}{c}$$

for $1 - R \ll 1$.

Solution 3

Part a   Students might assume that the perpendicular electric field is continuous across each of the mirrors. While this is not the intended solution, since the question tells us nothing about the internal workings of the mirror, they should get credit for this. If the electric field is continuous, then $1 + r = t$. Combined with $|r|^2 + |t|^2 = 1$, if r and t are real, these equations can only be satisfied if $(r, t) = (0, 1)$ or $(r, t) = (-1, 0)$. Since there is reflected and transmitted light in this problem, r and t must be complex numbers with a nonzero imaginary part.

Part b   Using Pythagorus's theorem, the angle between r and t must be $\pm 90°$ (see figure).

Part c   As in Solutions #2 and #3.

Part d   As in Solutions #2 and #3.
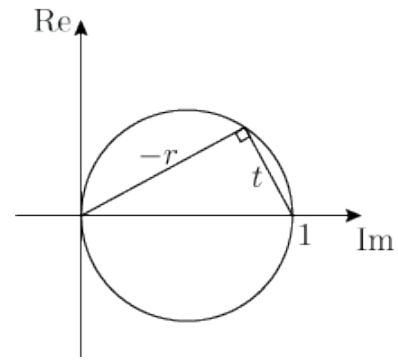
Solution 4

Here is an alternative approach to parts a and b that does not require complex numbers or a geometric series.

Parts a and b   Consider the first mirror in isolation and suppose a light wave is incident upon it from the left with amplitude A, as shown in the diagram below. The reflected wave will have amplitude $A\sqrt{R}$ and may undergo a phase shift; we use θ to denote its phase angle relative to the incident wave. Similarly, the transmitted wave has amplitude $A\sqrt{1 - R}$ and phase angle ψ relative to the incident wave.
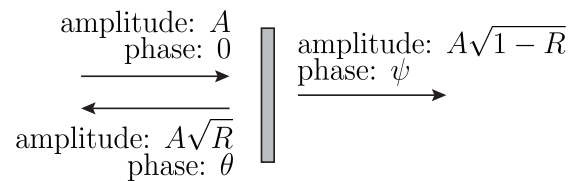
Now imagine a different scenario, in which there is a wave incident on the mirror from the right, as shown in Fig BLAH. This incident wave will have amplitude $A\sqrt{R}/\sqrt{1 - R}$ and a phase angle $\pi + \theta - \psi$. There will be a reflected wave with amplitude $AR/\sqrt{1 - R}$ (we multiply the amplitude by $\sqrt{R}$ upon reflection) and phase angle $\pi + 2\theta - \psi$ (we add θ to the phase upon reflection). There will be a transmitted wave with amplitude $A\sqrt{R}$ (we multiply the amplitude by $\sqrt{1 - R}$ upon reflection) and phase angle $\pi + \theta$ (we add ψ to the phase upon reflection).
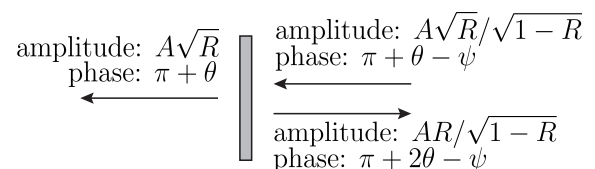
Now we consider the superposition of these two scenarios. On the left side, the waves travelling to the left cancel out, since they have the same amplitude but have phases differing by π. This destructive interference leaves a wave travelling to the right with amplitude A. This is exactly what is happening at the first mirror of the interferometer. On the right

side, there is a leftwards-propagating wave and two rightwards-propagating waves, as shown below.
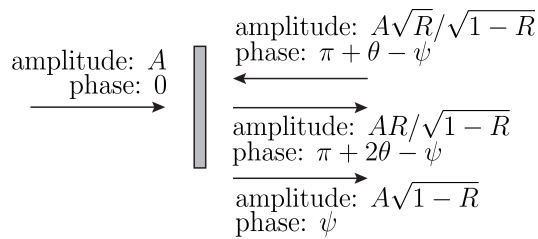
Now we use the fact that the mirror is lossless, so the light energy in the incoming waves in the figure above must equal the light energy in the outgoing waves. Since energy is proportional to the square of the electric field, the incoming energy flux is proportional to

$$I_{\text{in}} = A^2 + A^2 \left(\frac{R}{1-R} \right) \ .$$

The outgoing energy flux is a little trickier to work out, since there are two superimposed waves travelling out with different phases. It is

$$I_{\text{out}} = A^2(1-R) + A^2 \left(\frac{R^2}{1-R} \right) - 2A^2 R \cos\left(\pi + 2(\theta - \psi) \right) \ .$$

$I_{\text{in}} = I_{\text{out}}$ can be rearranged to give $\cos(\pi + 2(\theta - \psi)) = 0$, so $2(\theta - \psi)$ is a multiple of π and $\theta - \psi$ is $\pm\pi/2$. The reflected and transmitted waves must be out of phase by $90°$.

Grading

Part a

Part T3.a): Using sinusoidal waves	Pts.
understanding that some light is initially reflected without entering the interferometer	0.3
understanding that light bounces back and forth between the mirrors	0.3
using one or two travelling waves in each region	0.4
writing equations relating amplitudes via r and t	0.5
solving to obtain (16)	0.6
using $|r|^2 + |t|^2 = 1$ or $R + T = 1$	0.5
stating that this is a consequence of conservation of energy	0.2
indicating that the solutions r and t should be complex	0.2
Total on T3.a)	**3.0**

Part T3.a): Summing geometric series	Pts.
understanding that some light is initially reflected without entering the interferometer	0.3
understanding that light bounces back and forth between the mirrors	0.3
idea of superposition of complex amplitudes	0.2
correctly including the effect on the amplitudes of reflection, transmission and propagation	0.5
summing up complex amplitudes as a geometric series	0.4
obtaining (16)	0.4
using $|r|^2 + |t|^2 = 1$ or $R + T = 1$	0.5
stating that this is a consequence of conservation of energy	0.2
understanding that the solutions r and t should be complex	0.2
Total on T3.a)	**3.0**

Part T3.a): Assuming $1 + r = t$	Pts.
understanding that some light is initially reflected without entering the interferometer	0.3
understanding that light bounces back and forth between the mirrors	0.3
using $1 + r = t$	0.7
justification using continuity of electric field or thin-mirror arguments	0.8
using $|r|^2 + |t|^2 = 1$ or $R + T = 1$	0.5
stating that this is a consequence of conservation of energy	0.2
understanding that the solutions r and t should be complex	0.2
Total on T3.a)	**3.0**

Part b

Part T3.b: Algebraic method	Pts.
writing $90°$	0.5
taking modulus of (16) to get a condition involving r and t only	0.7
Solving with r, t, r^* and t^* to find that r is an imaginary number times t	0.8
Total on T3.b	**2.0**

Part T3.b: Geometric method	Pts.
writing $90°$	0.5
taking modulus of (16) to get a condition involving r and t only	0.7
using a geometric argument to show that r and t must make a right angle	0.8
Total on T3.b	**2.0**

Notes on T3.a) and T3.b): different conventions for r and t (eg using $-r$ instead of r, different phase factors) are allowed.

Part c

Part T3.c: Destructive interference	Pts.
$|B|$ and $|C|$ are the same if $|t| \ll |r|$	0.5
Applying symmetry to show $2E = U$	1.0
Finding relation between P' and P	1.5
Correct value for U	0.5
Correct value for E	0.5
Total on T3.c	**4.0**

Part T3.c: Geometric series	Pts.
Showing, perhaps just by reasoning, that the power propagating out through the first mirror decreases by a factor R^2 every Δt	1.5
Multiplying by Δt to convert power or intensity to energy	0.5
Summing a geometric series to find the total energy E	1.5
Correct value for E	0.5
Total on T3.c	**4.0**

Part d

Part T3.d: Removing waves	Pts.
Stated that energy reduces by factor R^2 each time a wave is removed	0.2
Using the fact that this reduction occurs at intervals Δt	0.4
Some valid mathematical argument from here that obtains the correct T when $1-R \ll 1$	0.4
Total on T3.d	**1.0**

Part T3.d: Exponential decay m	Pts.
Stated the decay is roughly exponential	0.2
State the outwards energy flux	0.4
Use this to determine decay constant	0.4
Total on T3.d	**1.0**

Notes on T3.d): no marks for dimensional analysis to obtain the combination L/c. The numerical prefactor is irrelevant provided it is order unity (e.g. $\ln 2$ for half-life). Any equivalent form, assuming $1-R \ll 1$, is acceptable.

E1 - Piezoelectricity - Solution

Task E.1 - Elasticity of the ball

The elasticity η can be computed as the ratio of the kinetic energy immediately before and after the bounce. Since the air drag is small, these energies are directly proportional to the dropping height h, or to the bouncing height h_b. In order to measure h or h_b as precisely as possible, it is necessary to devise a method to minimise parallax errors and take into the fact that the rule's zero is offset from its endpoint. Below is described one of the ways to do this.

We attach the ruler with the help of a peg onto one of the wings of the stand, fix (by sucking) a ball to the the black pipe of the release mechanism, and take the reading of the ruler at the lowest point of the hanging ball. We call this measured quantity s and it relates to h via the thickness of the wood on the bottom ($t = 4\,\mathrm{mm}$), and the starting height of the scale on the ruler ($z = 5\,\mathrm{mm}$) so that $h = s - t - z$.

We record the dropping and bouncing height for 4 different heights, and for each height, we repeat the experiment 5 times. With a linear fit (Fig. 1), we obtain a slope of $\gamma = (81 \pm 1)\% =: \eta$; therefore, the energy loss fraction $1 - \eta$ is expressed as

$$\frac{\Delta E}{E_0} = 1 - \eta = (19 \pm 1)\% \tag{1}$$

In the framework of this task, it would also be a valid, yet less precise method and therefore, awarded partial marks only, for each height to compute the ratio and take the average of these 4 ratios.
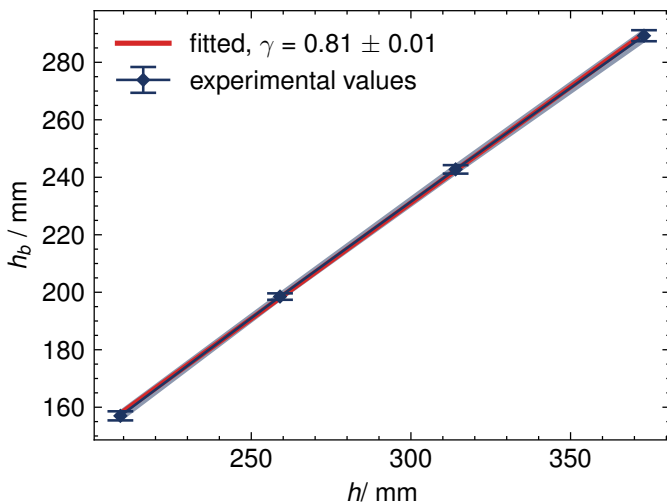

Figure 1

E.1 - Elasticity of the ball		Points
a	**Approach and Measurement**	**0.9**
	Idea that the fraction of kinetic energy after bounce can be found as h_b/h	0.3
	0.1 per each three measured pairs of heights (h and h_b), up to 9 pairs of heights, possibly with the same h	0.3
	0.1 per each different h value used, up to 3 values	0.3
b	**Evaluation and result**	**1.1**
	Graphical evaluation, or fit via calculator	0.5
	Alternatively: evaluation via point-wise average	or 0.3
	value of $1 - \eta$ * inside 0.19 ± 0.04	0.6
	OR value of $1 - \eta$ inside 0.19 ± 0.06	or 0.3
Total on E.1		**2.0**

Special cases and penalties

* If a student computes η instead of $1 - \eta$, full marks will still be given according to the table above.

• **Special case: multiple bounces** It is a valid approach to measure the time it takes for the ball to make several bounces for different heights or the total time it takes for the ball to stop bouncing. The theory behind that must be demonstrated to evaluate to a correctly linearized form of which η can be extracted but in that case one can receive full marks with that approach. If the approach is chosen without correct linearization, the first 0.3 points are deducted, the rest is graded normally, so a total 1.7 points would still be possible.

Task E.2 - Piezoelectric properties

a) Capacitance of the capacitor We charge the capacitor with the battery, connect it to the multimeter in the $2\,\mathrm{V}$ DC voltage range and switch off the battery using the top switch in the figure 2. If the bottom switch is not present, we start recording the time with the stopwatch the moment the switch is disconnected. If the bottom switch is present, we first disconnect the top switch, and start measuring time once the bottom switch is connected
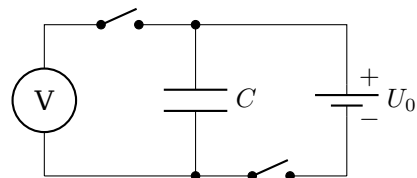

Figure 2

The capacitor now discharges via the inner resistance ($R_V = 11.1\,\mathrm{M\Omega}$) of the voltmeter. Every 5 seconds, we write down the voltage reading, see Tab. 2. The discharge of the capacitor can be described as:

$$\ln \frac{U(t)}{U_0} = -\frac{t}{R_V C} \tag{2}$$

We plot the data, fit it to a linear function and compute C from the slope (Fig. 3).
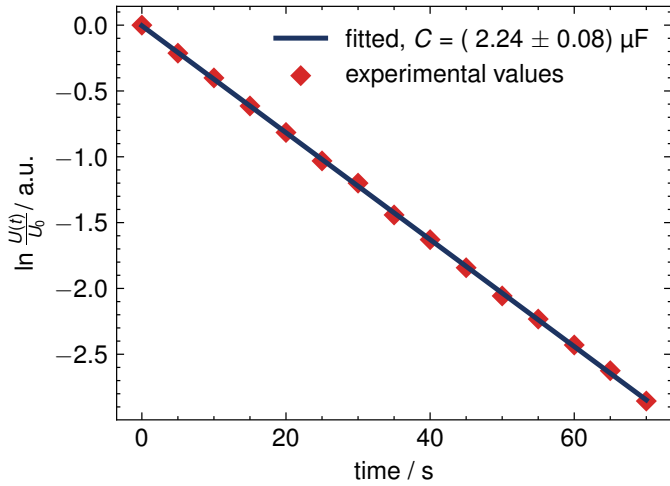

Figure 3

We finally obtain a capacitance of:

$$C = (2.24 \pm 0.08)\mu F \tag{3}$$

E.2a – Capacitance		Points
a	**Aproach and Measurement**	**0.9**
	Idea to use the inner resistance of the voltmeter to discharge (documented via circuit diagram!)	0.3
	Exponential decay of the capacitor voltage expressed equivalently to Eq. 2	0.2
	0.1 per measured $20\,\text{s}$, up to $40\,\text{s}$	0.2
	0.1 per 4 data points (voltage, time) up to 8 total data points	0.2
b	**Evaluation and result**	**1.1**
	A graphical evaluation, or a fit via a calculator	0.5
	Alternatively, a point-wise averages	or 0.3
	value of C within $(2.28 \pm 0.08)\mu F$	0.6
	OR value of C within $(2.28 \pm 0.12)\mu F$	or 0.3
Total on E.2a		**2.0**

Special cases and penalties

- *The reference capacitance in this grading scheme is the average of ca 20 capacitors and therefore differs slightly from Eq.(3).*
- *It is also possible to calculate the total charge $q = \int V/R\,dt$ leaving the capacitor during the discharge. In this case, the table above can be still used (0.2 will be awarded for $q = \int V/R\,dt$, instead of Eq. 2), and numerical integration substitutes the graphical evaluation.*

b) Capacitance of the piezo It can be noticed that the capacitance of the piezo element is much smaller than C, since with the same measurement technique as in E.2a, the piezo discharges too fast to take measurements of the direct discharging behaviour. However, with the provided switches and the capacitor,

one can build a circuit (Fig. 4) which enables us to go through multiple cycles of charging the piezo with the battery and then discharging it onto the much larger capacitance C.
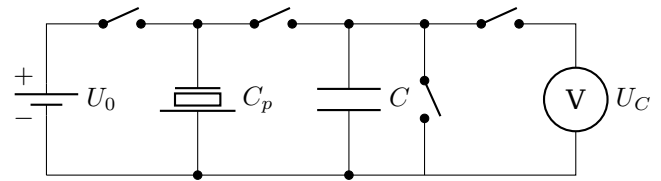
Figure 4: Circuit diagram for task E.2b
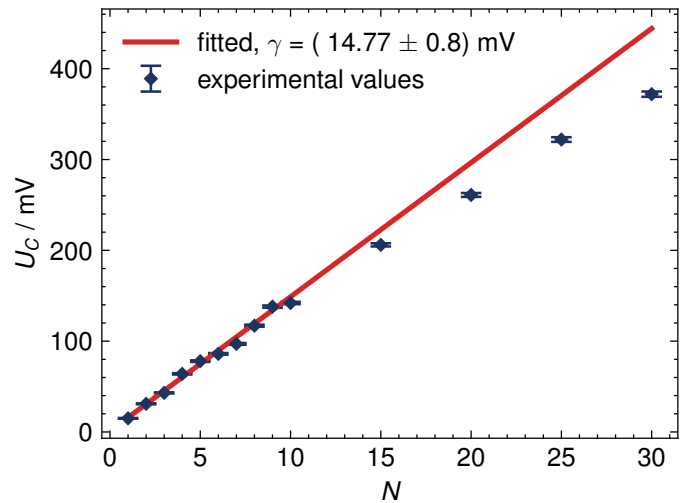
Figure 5

After a number of cycles (above 10), the voltmeter can be connected via a switch to measure the voltage of the capacitor U_C. After each voltage measurement, it is important to discharge both C and C_p, which can be done by two more switches in the circuit. We can now plot the capacitor voltage as a function of charging cycles (Fig. 5).

Detailed derivation After many charging cycles, the voltage across the capacitor approaches the voltage used to charge the piezo. With each cycle, the amount of charge transferred to the capacitor gets smaller.

Let us work out the charge transferred to the capacitor during the Nth charging cycle. Suppose it initially has voltage U_{N-1} across it, meaning it has stored charge $Q_{N-1} = CU_{N-1}$. Now connect the fully charged piezo, which has stored charge $Q_p = C_pU_0$. After connecting them together, the combined system acts as a single capacitor with stored charge $Q_{N-1} + Q_p$ and capacitance $C + C_p$, so the new voltage across the capacitor and the piezo is

$$U_N = \frac{Q_{N-1} + Q_p}{C + C_p}$$
$$= \frac{C}{C + C_p} U_{N-1} + \frac{C_p}{C + C_p} U_0 . \tag{4}$$

When the voltage saturates, the change in one charging cycle is negligible so $U_N = U_{N-1}$. In this case, (4) gives $U_N = U_{N-1} = U_0$; the voltage saturates at the voltage used to charge the piezo.

Suppose we are far from saturation, meaning $U_N \ll U_0$. Rewrite (4) as follows:

$$\frac{C}{C + C_p}(U_N - U_{N-1}) + \frac{C_p}{C + C_p} U_N = \frac{C_p}{C + C_p} U_0 . \quad (5)$$

The condition $U_N \ll U_0$ means we can approximate this as

$$\frac{C}{C + C_p}(U_N - U_{N-1}) = \frac{C_p}{C + C_p} U_0 ,$$

which has a simple linear solution

$$U_N = N \frac{C_p U_0}{C} . \quad (6)$$

This linear solution is a good approximation when $NC_p \ll C$. We measure $U_0 \approx 1.405\,\text{mV}$. Fitting this linear relation can be used to measure C_p. Here, the fit from Fig. 5 evaluates to

$$C_p = (23.5 \pm 2.4)\text{nF} \quad (7)$$

Note: the following precise calculations are not necessary for being awarded with full marks. The general solution to recursive equation (4) can be found as follows. Let $X_N = U_0 - U_N$, which is the distance of U_N from its saturation value. With this, (5) can be written as

$$X_N = \frac{C}{C + C_p} X_{N-1} .$$

The initial condition is $U_0 = 0$, which means $X_0 = U_0$. Then

$$X_N = \left(\frac{C}{C + C_p} \right)^N U_0 .$$

Returning to the original variables, we arrive at

$$U_N = U_0 - \left(\frac{C}{C + C_p} \right)^N U_0 . \quad (8)$$

Indeed, in the limit $N \to \infty$, this result gives the same saturation value that we found above.

Students are expected to fit the linear model $U_N \propto N$. However, if they use (8) and fitting to

$$\log\left(\frac{U_0 - U_N}{U_0} \right) = N \log\left(\frac{C}{C + C_p} \right), \quad (9)$$

they will also get full marks.

E.2b – Capacitance of the piezo		Points
a	**Aproach and Measurement**	**1.4**
	Measurement technique to charge piezo (documented via circuit diagram!)	0.1
	discharge onto capacitor (documented via circuit diagram!)	0.2
	Idea to repeat multiple times to increase precision (multiple charging cycle idea)	0.4
	0.1 per measured 2 cycles, up to 6 cycles and after that 0.1 per measured 4 cycles up to 10	0.4
	0.1 per repetition per data point, up to 3 repetitions per point	0.3
b	**Evaluation and result**	**1.1**
	Approximation $NC_p \ll U_0$ leading to Eq. 6 and only taking into account values up to 15 charge cycles	0.5
	OR using Eq. 6 and only taking into account values up to 20 charge cycles	or 0.3
	OR exact solution like eq. 8 for arbitrary measurement range (also large cycle numbers allowed)	or 0.5
	value of C_p inside (23.5 ± 3)nF	0.6
	OR value of C_p inside (23.5 ± 5)nF	or 0.3
Total on E.2b		**2.5**

Special cases and penalties

- -0.1 if U_0 was assumed to be $1.5\,\text{V}$ instead of measuring it.
- If no circuit diagram was provided, the first 0.3 points are deducted for the measurement technique and discharging the piezo on the capacitor.
- **Capacitor parallel to piezo case:** This was quite common: If the student repeated the measurement from task E.2a but with the parallel circuit of piezo and capacitor (hence, measuring the sum of capacities), this is still a very imprecise measurement technique because the relative error will be on the order of the value that we seek to measure. It will however be possible to receive the following partial points if everything else was done as required:
  - 0.1 for measurement technique
  - 0 for discharge on capacitor idea
  - 0 for multiple charging cycles
  - 0 for measured cycle number
  - up to 0.3 for repetitions
  - 0.2 for approach of using parallel capacitor
  - max. 0.3 for correct value ± 5 nF range.
  - so, a maximum total of 0.9 points can be awarded.
- **Penalty: Student discharges piezo directly via Voltmeter** If the student has only used a circuit that consists of the voltmeter and the piezo, (like in E.2a), the student always receives only the first 0.1 points for the entire task, given that they drew the circuit, else, 0 points.

c) Response function To measure the piezo voltage as a function of force, we assemble the circuit like shown in Fig. 6 and operate it as follows:
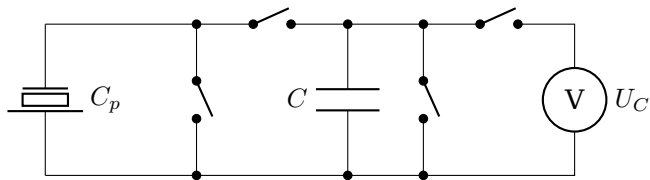
Figure 6: .

Note that we need the capacitor, because if we were to connect the voltmeter directly to the piezo, it would discharge faster than we are able to take a reading. We place the piezo element on the scales and push down on the scales, while the switch connecting it to the capacitor is closed. When the desired weight is reached, we cut the capacitor off and release the weight from the scales. The voltage under load has been transferred to the capacitor and can now, via the voltmeter, be read out. Via $F = mg$ we can compute the force from the displayed mass values and by multiplying with C/C_p, we obtain the piezo voltages from the capacitor voltages, using $C_p \ll C$. We repeat the measurement 5 times per weight value to get an idea of fluctuations and utilize average values; the data can found in Table 4. The plot shown in Fig. 7 is achieved if we use most of the permitted force range of the scales.
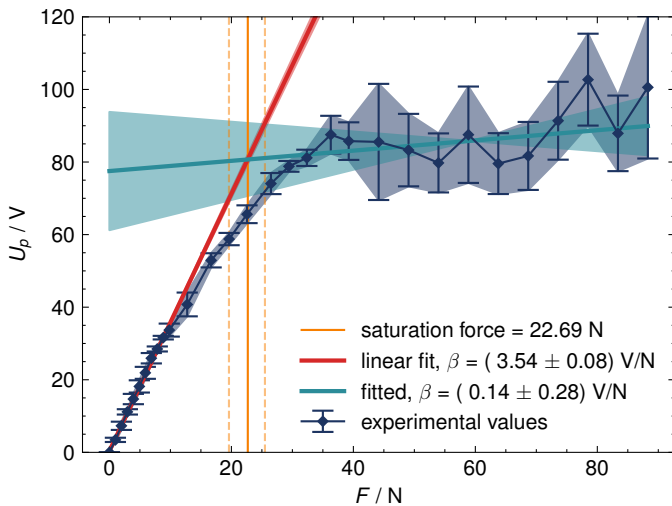

Figure 7

For large values of F, the voltages become noisy and seem to saturate (see next sub-task). However, the dependence is fairly linear up to ca $10\,\mathrm{N}$. We can fit that range and obtain a piezo voltage coefficient

$$\beta = (3.37 \pm 0.1)\mathrm{V/N} \tag{10}$$

E.2c – Response function		Points
a	**Approach**	**0.9**
	The idea to charge the capacitor using the piezo	0.4
	and measure afterwards the capacitor voltage with voltmeter	0.1
	using switch to discharge piezo (documented via circuit diagram or detailed description!)	0.4
b	**Measurement** If they did not discharge the piezo before each individual measurement, or if there are obvious points of piezo-zero floating, we half the measurement points	**1.9** or **0.9**
	0.05 for each measurement at a different weight (forces) value, up to for 16 data points; the result is to be rounded down to the precision of 0.1	0.8
	0.1 per data points within each $1\,\mathrm{kg}$-wide weight range, up to $6\,\mathrm{kg}$	0.6
	0.1 per repetition per data point (average number of repetitions for the entire measurement series), up to 5 repetitions per point	0.5
c	**Evaluation and result**	**1.2**
	Accurate plot of the data points	0.3
	Graphical evaluation of the slope, or fit with calculator of linear region OR point-wise average of linear region	0.4 or 0.2
	value of β inside $(3.54 \pm 0.2)\mathrm{V/N}$ OR value of β inside $(3.54 \pm 0.4)\mathrm{V/N}$	0.5 or 0.3
Total on E.2c		**4.0**

Special cases and penalties

- If no circuit diagram was provided, the first 0.9 points for the Approach are not awarded.
- If the student uses only the voltmeter, to measure directly the piezo voltage, the results will not be reliable because the piezo discharges very quickly via the voltmeter, with the RC-time being equal to $20\,\mathrm{ms}$. Therefore, this approach is very inaccurate, and no points ($0/0.9$) are given for the approach. For the measurements, only 50% of points can be given ($0.9/1.9$) points if an instantaneous voltage reading is taken after applying a force AND the result differs from the value that is expected for the given force no more than by a factor of 2.0. The points for Evaluation and result can be graded according to the table above.

d) Saturation If we already measured large enough weight values in the previous task, we can just use the data from there, otherwise, we record more data over a larger range now. Due to the noise in the saturated region, it is important to use multiple measurements per point and take the average. The saturation point can be found by computing the intersection of the fitting functions of the linear region for low forces and the saturated region, just as visible in Fig. 7. We can read out the relevant values, having measured the area of the piezo as $A_p = \pi r_p^2 \approx 4.15 \, 10^{-4}\mathrm{m}^2$:

$$U_{sat} = (86 \pm 16)\mathrm{V} \tag{11}$$

and

$$p_{sat} = F_{sat}/A_p = (55000 \pm 7000)\mathrm{Pa} \tag{12}$$

and therefore,

$$\sigma_{max} = \frac{C_p U_{sat}}{A} = (4.9 \pm 0.9)\text{mC/m}^2 \qquad (13)$$

E.2d – Saturation		Points
a	**Aproach and Measurement**	**0.6**
	Determination method of saturation point as intersection of extreme region fit functions (using data from Figure 7)	0.4
	Formula Eq. 13	0.2
b	**Evaluation and result**	**0.9**
	Graphical evaluation, or calculation of intersection	0.3
	value of U_{sat} inside (86 ± 25)V	0.2
	value of p_{sat} from 40kPa to 85kPa	0.2
	value of σ_{max} inside (4.9 ± 2)mC/m^2	0.2
Total on E.2d		**1.5**

Special cases and penalties

- If measurements additional to what have been done for E.2c are made here, these are to be taken into account while grading E-2c-b.
- **Common case** If the saturation was not determined via a plot but simply by pressing and ballparking the force at which the voltage does not rise anymore, we can award points up to the following maxima:
  - $0.2/0.4$ for evaluation method (because it works in principle but can be very imprecise)
  - 0.2 if the formula was given
  - 0 for graphical evaluation - at least a plot with meaningfull graphical interpretation (could be the one from E.2c) is required to correctly assess the situation here. Without (which is this common case) it's 0.
  - max 3×0.2 for all remaining values, graded just normally.
  - So a total of $1.0/1.5$ points can be awarded for this technique.
- **Penalty:** Without a way to quantitatively measure piezo voltage responses to applied forces in E.2c, (especially if E.2c was not done or measurements were only attempted with a voltmeter directly attached to the piezo without anything else), this task can not be done in a way that is physically meaningfull and it will always receive 0 points.

Task E.3 - Small area behaviour

We can use the setup from the task E.2c, but instead of loading the whole surface of the piezo, we will use the wooden stick to poke into a hole of the plywood cover and measure F_s with the scales as before.

By plotting $U_p(F_s)$ (Fig. 8), we find it has almost the same dependence as in part E2.c with the slope coefficient $\beta_s = (3.37 \pm 0.1)$V/N almost the same as β from part E2.c.
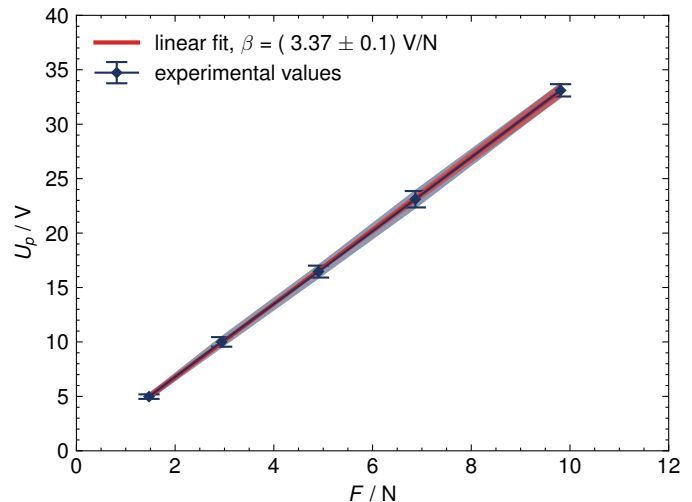

Figure 8

It seems counter-intuitive that limiting the area drastically does not change the response, because the top electrode of the piezo is thin and flexible. What we are observing in this experiment can be explained as follows. Pressing with a stick creates a voltage across the piezo that leads to a mechanical stress radially inside the crystal. The thick bottom electrode prevents the crystal bottom part contracting radially. At the same time, the top electrode is thin, and would be free to contract if there were no wooden plate. Such a contraction would cause the piezo crystal to curve into a bowl-like shape. The wooden cover plate prevents that happening; this means that the mechanical stress will grow along the rim of the piezo disc, and decrease at the point where we press. As a result, the pressure is effectively distributed over the entire piezo crystal. Therefore the correct answer to this part is that there are no significant changes in the response.

E.3 - Small area effects	Points
Idea to use the stick through the hole for exposing a limited area to pressure	0.5
Adequate measurement of U_p for different values of force	0.3
Correct result: No significant change.	0.2
Total on E.3	**1.0**

Special cases and penalties

- **Penalty:** Without an explicit drawing or written description that the stick was put through the hole, the corresponding 0.5 and the 0.2 for the result will not be awarded, since there is no proof that the measurement are meaningful for this part. The same holds for approaches that only put smaller areas of the wooden cover plate under pressure.
- Adequate measurements of U_p should have at least three points for different forces and it should be concludable (but does not need to be calculated explicitly by the student) from that data that the slope is the same as in E.2c within the error margins. For 2 measurements we award 0.2 and for one 0.1 points, still.
- **Penalty:** Without a reproducable way to measure piezo voltage responses to applied forces in E2.c, (especially if E2.c was not done or measurements were only attempted with a voltmeter directly attached to the piezo without anything else), the measurements and conclusion in this task are not meaningful. Therefore, the stu-

dent can only receive max. 0.5 points for the idea of applying pressure through the whole but nothing else. Otherwise the student receives 0 points total.

Task E.4 - Deformation of the ball

When the ball is dropped onto the piezo element, the kinetic energy just before the collision is partially converted into elastic deformation and the remainder dissipated as heat and sound. At the point of maximal deformation, the kinetic energy is zero and the force on the ball and piezo is also at its maximum. By using the diode that is soldered to the capacitor, we can prevent charges from flowing backwards and therefore store the maximum voltage during the measurement. You can see the corresponding circuit diagram in Fig. 9.
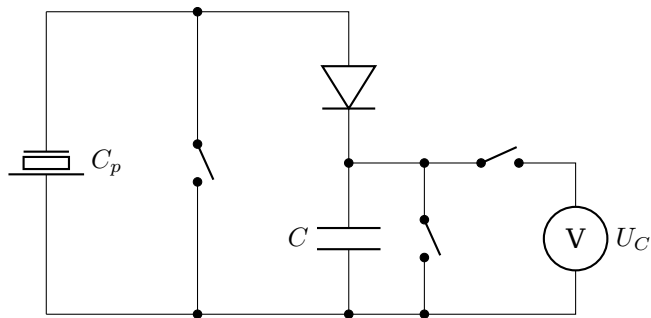

Figure 9: .

If we drop the ball onto the piezo element from different heigths, we will provide different kinetic energies before the impact. Each time, we read the maximum voltage from the capacitor and convert it into piezo voltage by multiplying with C/C_p. Multiplying again with the linear slope β found in task E.2c, we get the maximum force during the impact F_m. With that, we can, for each initial kinetic energy, compute the maximum deformation x_m.

$$F = k x_m^{\alpha} \Rightarrow x_m = \left(\frac{F}{k}\right)^{1/\alpha} \qquad (14)$$

We integrate the force and find the maximum elastic energy the ball reaches during the collision.

$$E_{elastic} = \int_0^{x_m} F(x)\mathrm{d}x = \frac{1}{\alpha+1} k x_m^{\alpha+1} = \frac{k^{-1/\alpha}}{\alpha+1} F_m^{1+1/\alpha} \qquad (15)$$

From task E.1, we can express the elastic energy of the ball, when dropped from height h:

$$E_{elastic} = \eta m g h \qquad (16)$$

where $m = (8 \pm 0.5)g$ can be measured using the scales. Using that, we can plot the elastic energy as a function of the maximum force. However, this linear plot (Fig. 10) was not required from the students, we only show it here for illustration.
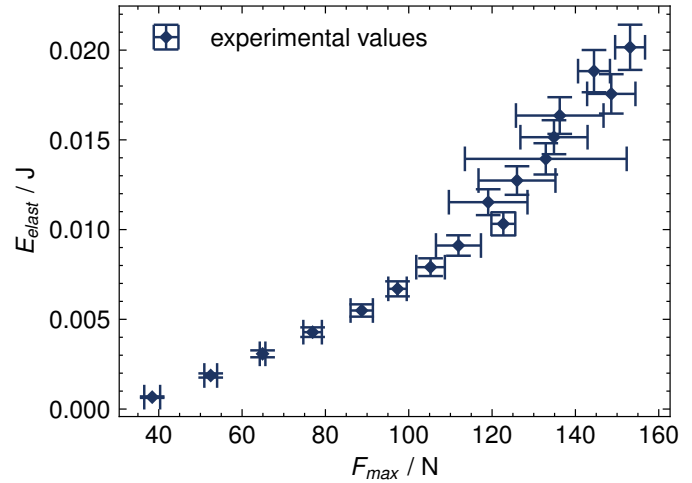
Figure 10

Taking the logarithm of both F_m and $E_{elastic}$, we arrive at a linear function, which we can plot (Fig. 11).

$$\ln E_{elastic} = \ln \frac{k^{-1/\alpha}}{\alpha+1} + \left(1 + \frac{1}{\alpha}\right)\ln F_m \ . \qquad (17)$$
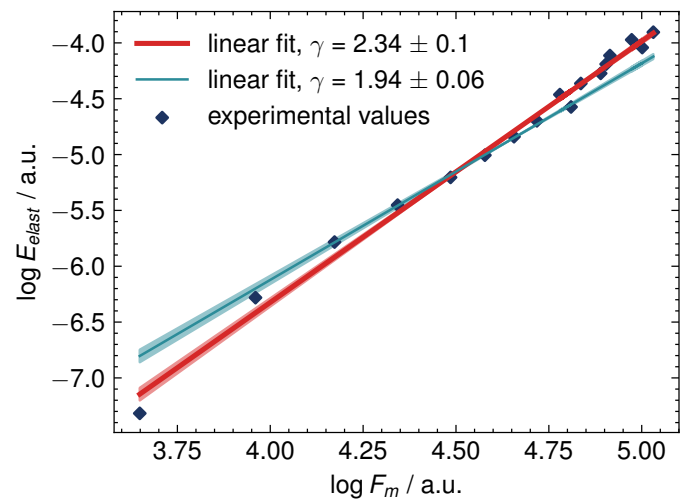
Figure 11

Extracting the slope γ, we arrive at a value of α of:

$$\gamma = \left(1 + \frac{1}{\alpha}\right) \Rightarrow \alpha = \frac{1}{\gamma - 1} \approx 0.75 \pm 0.06 \ , \qquad (18)$$

A more correct way is to take into account only the nicely linear region in the center of the range. The reason for dropping the leftmost datapoint is that the relative uncertainty of the underlying height measurement is very low. The reason for dropping the rightmost datapoints lies in the force-voltage curve: we are already starting to approach the saturation region.

$$\gamma_2 = \approx 1.06 \pm 0.05 \ . \qquad (19)$$

Note: This result is actually surprising, since, according to the Hertz theory, we would have expected an exponent

of $3/2$. *This is again something related to the piezo element being glued to the plates: while the crystal tries to take a bowl-like shape, plate moves slightly towards the ball, hence the deformation of the ball does no longer strictly correspond to its displacement during the impact.*

With Eq. 17, we can compute k from the interception of the fit ($y_0 = -15.7$), so:

$$k = ((\exp y_0)(\alpha + 1))^{-\alpha} \approx (84000 \pm 7000) \mathrm{N/m}^\alpha \quad (20)$$

E.4 – Deformation of the ball	Points
a	**Aproach**	**1.5**
	Idea to use the diode in combination with the capacitor for extracting the maximum piezo voltage during a drop	0.5
	using switch to discharge piezo (documented via circuit diagram or detailed description!)	0.5
	Approach that the elastic kinetic energy part from dropping is the same as deformation energy	0.5
b	**Measurement**	**1.0** or **0.5**
	If the piezo has not been discharged before each individual measurement, the points are halved (it is assumed that the piezo has not been discharged if the voltage readings of the datapoints fluctuate significantly around the expected values)	
	0.1 per measured 2 height values, up to 8 different height values	0.4
	0.1 per measured $10\,\mathrm{cm}$ of height range	0.3
	0.1 per repetition per data point, up to 3 repetitions	0.3
c	**Evaluation and result**	**2.0**
	Linearisation equivalent to Eq. 17	0.8
	Graphical evaluation for α and k, or fit via calculator	0.7
	Value of α between 1 ± 0.5	0.3
	Value of k between $(84000 \pm 40000) \mathrm{N/m}^\alpha$	0.2
Total on E.4		**4.5**

Special cases and penalties

- *If no circuit diagram was provided, the first 1.0 points are deducted for the measurement technique with the diode and discharging the piezo on the capacitor.*
- *If the voltmeter has been used directly for measuring the piezo voltage (without capacitor and diode), the data are unusable. Therefore, we cannot award the first $0.5 + 0.5$ points in the approach, and also, no points are awarded for the measurement data taken. However, for the evaluation part, we do not subtract points even if it is done with these unusable data as long as a correct evaluation method has been used.*

Task E.5 - Interaction time

When the less elastic ball bounces, we can estimate the change of its momentum Δp_1 as:

$$\Delta p_1 = \int_t F_1(t)\mathrm{d}t = \frac{a_1}{b_1} \int f(t)\mathrm{d}t \propto F_{1\max}\tau_1,$$

where $F_{1\max} = a_1 F_{0\max}$ is the maximal force during the collision and $\tau_1 \approx \tau_0/b_1$ is the interaction time.

In other words,

$$\frac{\Delta p_1}{\Delta p_0} = \frac{v_1}{v_0} = \frac{F_{1\max}}{F_{0\max}} \cdot \frac{\tau_1}{\tau_0}.$$

By measuring $v_1/v_0 = \sqrt{h_1/h_0}$ and $\frac{F_{1\max}}{F_{0\max}} = \frac{U_1}{U_0}$, we can estimate the time scaling τ_1/τ_0:

$$\frac{U_1}{U_0} = \frac{\tau_1}{\tau_0} \cdot \frac{\sqrt{h_1}}{\sqrt{h_0}}, \qquad \text{or} \qquad \tau \propto \frac{U}{\sqrt{h}}$$

The measurements are in the table 7. We plot the dependency of $U/\sqrt{h_1}$ on $\sqrt{h_1}$ and find that it is horizontal up to the measurement errors (Fig. 12). In other words, τ does not change too much within the range of forces.
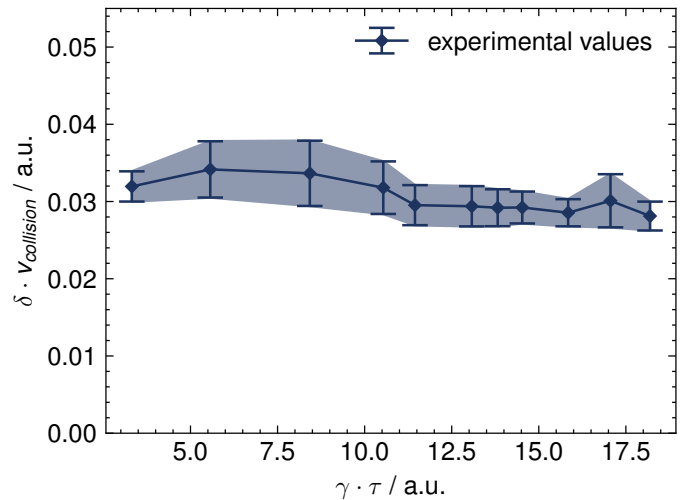
Figure 12

E.5 – Interaction time	Points
Theory	**0.5**
find how a_1/b_1 depends on v	0.3
express it through measurable ratios	0.2
Measurements and plots	**1.5**
0.1 per measured force value, up to 7 different force values	0.7
0.1 per repetition per data point, up to 3 repetitions	0.3
Plot	0.2
coordinates are related to theory	0.3
Conclusion (τ doesn't depend on v)	**0.5**
Total on E.5	**2.5**

Experiment 2024 - General Grading Scheme

General remarks for grading

- For minor mistakes (like minus-sign, factor-2 wrong or just the inverse of a result), we deduct only -0.1 points once, and will grade the remaining task as if the mistake was corrected (no penalty for a propagating error), including the numerical results.
- Even if the data used for making a plot is of low quality because of an inferior measurement technique, the points designated for plotting are not reduced as long as the data points are marked correctly according to the tabulated data.

E.1 - Elasticity of the ball		Points
a	**Aproach and Measurement**	**0.9**
	Idea that the fraction of kinetic energy after bounce can be found as h_b/h	0.3
	0.1 per each three measured pairs of heights (h and h_b), up to 9 pairs of heights, possibly with the same h	0.3
	0.1 per each different h value used, up to 3 values	0.3
b	**Evaluation and result**	**1.1**
	Graphical evaluation, or fit via calculator	0.5
	Alternatively: evaluation via point-wise average	or 0.3
	value of $1 - \eta$ * inside 0.19 ± 0.04	0.6
	OR value of $1 - \eta$ inside 0.19 ± 0.06	or 0.3
Total on E.1		**2.0**

Special cases and penalties

- * If a student computes η instead of $1 - \eta$, full marks will still be given according to the table above.
- **Special case: multiple bounces** It is a valid approach to measure the time it takes for the ball to make several bounces for different heights or the total time it takes for the ball to stop bouncing. The theory behind that must be demonstrated to evaluate to a correctly linearized form of which η can be extracted but in that case one can receive full marks with that approach. If the approach is chosen without correct linearization, the first 0.3 points are deducted, the rest is graded normally, so a total 1.7 points would still be possible.

E.2a – Capacitance		Points
a	**Aproach and Measurement**	**0.9**
	Idea to use the inner resistance of the voltmeter to discharge (documented via circuit diagram!)	0.3
	Exponential decay of the capacitor voltage expressed equivalently to Eq. 2	0.2
	0.1 per measured $20\,\text{s}$, up to $40\,\text{s}$	0.2
	0.1 per 4 data points (voltage, time) up to 8 total data points	0.2
b	**Evaluation and result**	**1.1**
	A graphical evaluation, or a fit via a calculator	0.5
	Alternatively, a point-wise averages	or 0.3
	value of C within $(2.28 \pm 0.08)\mu\text{F}$	0.6
	OR value of C within $(2.28 \pm 0.12)\mu\text{F}$	or 0.3
Total on E.2a		**2.0**

Special cases and penalties

- The reference capacitance in this grading scheme is the average of ca 20 capacitors and therefore differs slightly from Eq.(3).
- It is also possible to calculate the total charge $q = \int V/R\mathrm{d}t$ leaving the capacitor during the discharge. In this case, the table above can be still used (0.2 will be awarded for $q = \int V/R\mathrm{d}t$, instead of Eq. 2), and numerical integration substitutes the graphical evaluation.

E.2b – Capacitance of the piezo		Points
a	**Aproach and Measurement**	**1.4**
	Measurement technique to charge piezo (documented via circuit diagram!)	0.1
	discharge onto capacitor (documented via circuit diagram!)	0.2
	Idea to repeat multiple times to increase precision (multiple charging cycle idea)	0.4
	0.1 per measured 2 cycles, up to 6 cycles and after that 0.1 per measured 4 cycles up to 10	0.4
	0.1 per repetition per data point, up to 3 repetitions per point	0.3
b	**Evaluation and result**	**1.1**
	Approximation $NC_p \ll U_0$ leading to Eq. 6 and only taking into account values up to 15 charge cycles	0.5
	OR using Eq. 6 and only taking into account values up to 20 charge cycles	or 0.3
	OR exact solution like eq. 8 for arbitrary measurement range (also large cycle numbers allowed)	or 0.5
	value of C_p inside $(23.5 \pm 3)\text{nF}$	0.6
	OR value of C_p inside $(23.5 \pm 5)\text{nF}$	or 0.3
Total on E.2b		**2.5**

Special cases and penalties

- -0.1 if U_0 was assumed to be $1.5\,\text{V}$ instead of measuring it.
- If no circuit diagram was provided, the first 0.3 points are deducted for the measurement technique and discharging the piezo on the capacitor.
- **Capacitor parallel to piezo case:** This was quite common: If the student repeated the measurement from task E.2a but with the parallel circuit of piezo and capacitor (hence, measuring the sum of capacities), this is still a very imprecise measurement technique because the relative error will be on the order of the value that we seek to measure. It will however be possible to receive the following partial points if everything else was done as required:
  - 0.1 for measurement technique
  - 0 for discharge on capacitor idea
  - 0 for multiple charging cycles
  - 0 for measured cycle number
  - up to 0.3 for repetitions
  - 0.2 for approach of using parallel capacitor
  - max. 0.3 for correct value ± 5 nF range.
  - so, a maximum total of 0.9 points can be awarded.
- **Penalty: Student discharges piezo directly via Voltmeter** If the student has only used a circuit that consists of the voltmeter and the piezo, (like in E.2a), the student always receives only the first 0.1 points for the entire task, given that they drew the circuit, else, 0 points.

E.2c – Response function		Points
a	**Approach**	**0.9**
	The idea to charge the capacitor using the piezo	0.4
	and measure afterwards the capacitor voltage with voltmeter	0.1
	using switch to discharge piezo (documented via circuit diagram or detailed description!)	0.4
b	**Measurement** If they did not discharge the piezo before each individual measurement, or if there are obvious points of piezo-zero floating, we half the measurement points	**1.9** or **0.9**
	0.05 for each measurement at a different weight (forces) value, up to for 16 data points; the result is to be rounded down to the precision of 0.1	0.8
	0.1 per data points within each 1 kg-wide weight range, up to 6 kg	0.6
	0.1 per repetition per data point (average number of repetitions for the entire measurement series), up to 5 repetitions per point	0.5
c	**Evaluation and result**	**1.2**
	Accurate plot of the data points	0.3
	Graphical evaluation of the slope, or fit with calculator of linear region OR point-wise average of linear region	0.4 or 0.2
	value of β inside (3.54 ± 0.2)V/N OR value of β inside (3.54 ± 0.4)V/N	0.5 or 0.3
Total on E.2c		**4.0**

Special cases and penalties

- If no circuit diagram was provided, the first 0.9 points for the Approach are not awarded.
- If the student uses only the voltmeter, to measure directly the piezo voltage, the results will not be reliable because the piezo discharges very quickly via the voltmeter, with the RC-time being equal to 20 ms. Therefore, this approach is very inaccurate, and no points (0/0.9) are given for the approach. For the measurements, only 50% of points can be given (0.9/1.9) points if an instantaneous voltage reading is taken after applying a force AND the result differs from the value that is expected for the given force no more than by a factor of 2.0. The points for Evaluation and result can be graded according to the table above.

E.2d – Saturation		Points
a	**Aproach and Measurement**	**0.6**
	Determination method of saturation point as intersection of extreme region fit functions (using data from Figure 7)	0.4
	Formula Eq. 13	0.2
b	**Evaluation and result**	**0.9**
	Graphical evaluation, or calculation of intersection	0.3
	value of U_{sat} inside (86 ± 25)V	0.2
	value of p_{sat} from 40kPa to 85kPa	0.2
	value of σ_{max} inside (4.9 ± 2)mC/m^2	0.2
Total on E.2d		**1.5**

Special cases and penalties

- If measurements additional to what have been done for E.2c are made here, these are to be taken into account while grading E-2c-b.
- **Common case** If the saturation was not determined via a plot but simply by pressing and ballparking the force at which the voltage does not rise anymore, we can award points up to the following maxima:
  - 0.2/0.4 for evaluation method (because it works in principle but can be very imprecise)
  - 0.2 if the formula was given
  - 0 for graphical evaluation - at least a plot with meaningfull graphical interpretation (could be the one from E.2c) is required to correctly assess the situation here. Without (which is this common case) it's 0.
  - max 3×0.2 for all remaining values, graded just normally.
  - So a total of 1.0/1.5 points can be awarded for this technique.
- **Penalty:** Without a way to quantitatively measure piezo voltage responses to applied forces in E.2c, (especially if E.2c was not done or measurements were only attempted with a voltmeter directly attached to the piezo without anything else), this task can not be done in a way that is physically meaningfull and it will always receive 0 points.

E.3 – Small area effects		Points
	Idea to use the stick through the hole for exposing a limited area to pressure	0.5
	Adequate measurement of U_p for different values of force	0.3
	Correct result: No significant change.	0.2
Total on E.3		**1.0**

Special cases and penalties

- **Penalty:** Without an explicit drawing or written description that the stick was put through the hole, the corresponding 0.5 and the 0.2 for the result will not be awarded, since there is no proof that the measurement are meaningful for this part. The same holds for approaches that only put smaller areas of the wooden cover plate under pressure.
- Adequate measurements of U_p should have at least three points for different forces and it should be concludable (but does not need to be calculated explicitly by the student) from that data that the slope is the same as in E.2c within the error margins. For 2 measurements we award 0.2 and for one 0.1 points, still.
- **Penalty:** Without a reproducable way to measure piezo voltage responses to applied forces in E2.c, (especially if E2.c was not done or measurements were only attempted with a voltmeter directly attached to the piezo without anything else), the measurements and conclusion in this task are not meaningful. Therefore, the student can only receive max. 0.5 points for the idea of applying pressure through the whole but nothing else. Otherwise the student receives 0 points total.

E.4 – Deformation of the ball		Points
a	**Aproach**	**1.5**
	Idea to use the diode in combination with the capacitor for extracting the maximum piezo voltage during a drop	0.5
	using switch to discharge piezo (documented via circuit diagram or detailed description!)	0.5
	Approach that the elastic kinetic energy part from dropping is the same as deformation energy	0.5
b	**Measurement** If the piezo has not been discharged before each individual measurement, the points are halved (it is assumed that the piezo has not been discharged if the voltage readings of the data-points fluctuate significantly around the expected values)	**1.0** or **0.5**
	0.1 per measured 2 height values, up to 8 different height values	0.4
	0.1 per measured $10\,\text{cm}$ of height range	0.3
	0.1 per repetition per data point, up to 3 repetitions	0.3
c	**Evaluation and result**	**2.0**
	Linearisation equivalent to Eq. 17	0.8
	Graphical evaluation for α and k, or fit via calculator	0.7
	Value of α between 1 ± 0.5	0.3
	Value of k between $(84000 \pm 40000)\text{N}/\text{m}^{\alpha}$	0.2
Total on E.4		**4.5**

Special cases and penalties

- *If no circuit diagram was provided, the first 1.0 points are deducted for the measurement technique with the diode and discharging the piezo on the capacitor.*
- *If the voltmeter has been used directly for measuring the piezo voltage (without capacitor and diode), the data are unusable. Therefore, we cannot award the first $0.5 + 0.5$ points in the approach, and also, no points are awarded for the measurement data taken. However, for the evaluation part, we do not subtract points even if it is done with these unusable data as long as a correct evaluation method has been used.*

E.5 – Interaction time		Points
	Theory	**0.5**
	find how a_1/b_1 depends on v	0.3
	express it through measurable ratios	0.2
	Measurements and plots	**1.5**
	0.1 per measured force value, up to 7 different force values	0.7
	0.1 per repetition per data point, up to 3 repetitions	0.3
	Plot	0.2
	coordinates are related to theory	0.3
	Conclusion (τ doesn't depend on v)	**0.5**
Total on E.5		**2.5**

Raw data tables

Table 1: Data for 1

S	364	305	250	200
$s1$	286	237	195	152
$s2$	286	241	193	151
$s3$	287	239	194	154
$s4$	282	238	196	155
$s5$	286	237	193	155
h	373	314	259	209
$h1$	290	241	199	156
$h2$	290	245	197	155
$h3$	291	243	198	158
$h4$	286	242	200	159
$h5$	290	241	197	159

Table 2: Data for 2a

U	t
mV	s
1408	0
1138	5
943	10
762	15
623	20
502	25
424	30
333	35
276	40
223	45
180	50
151	55
124	60
102	65
81	70

Table 3: Data for 2b

charges	U_c
	mV
1	15
2	31
3	43
4	64
5	78
6	86
7	97
8	117
9	138
10	142
15	206
20	261
25	322
30	372

Table 4: Data for 2c

m	$U1$	$U2$	$U3$	$U4$	$U5$
kg	mV	mV	mV	mV	mV
0.0	0	0	0	0	0
0.1	30	34	39	42	37
0.2	63	78	87	82	77
0.3	126	110	119	119	116
0.4	142	173	153	156	153
0.5	176	206	187	186	206
0.6	240	224	216	249	230
0.7	286	285	259	270	272
0.8	304	295	306	306	296
0.9	335	328	337	338	334
1.0	367	346	373	357	339
1.3	429	390	447	432	458
1.7	557	576	550	541	575
2.0	620	629	625	635	600
2.3	702	711	711	676	671
2.7	812	798	759	762	787
3.0	823	847	820	838	841
3.3	856	855	840	888	854
3.7	994	911	926	916	884
4.0	977	881	881	887	911
4.5	1060	1024	830	799	812
5.0	977	918	852	893	766
5.5	954	817	789	820	839
6.0	802	890	907	1089	942
6.5	892	736	836	903	842
7.0	985	867	859	815	795
7.5	984	968	833	1068	981
8.0	1110	993	1247	1022	1061
8.5	988	814	971	1003	874
9.0	1181	1267	944	1022	907

Table 5: Data for 3

m	$U1$	$U2$	$U3$	$U4$	$U5$	$U6$
kg	mV	mV	mV	mV	mV	mV
0.15	52	50	49	55	52	56
0.3	105	102	98	109	111	110
0.5	175	178	166	184	170	172
0.7	245	250	258	233	242	239
1.0	355	340	354	351	345	357

Table 6: Data for 4

S	h	$U1$	$U2$	$U3$	$U4$	$U5$
mm	mm	mV	mV	mV	mV	mV
363	334	437	411	410	424	422
341	312	399	395	380	398	413
320	291	411	414	414	378	425
300	271	337	358	423	385	369
280	251	356	345	393	401	358
260	231	320	311	361	461	373
240	211	303	364	361	332	371
220	191	315	340	329	287	365
200	171	332	326	336	345	347
180	151	305	322	280	316	315
160	131	297	297	284	295	273
140	111	276	271	269	260	261
120	91	253	238	235	241	252
100	71	215	203	205	217	217
80	51	178	177	176	180	181
60	31	150	141	138	146	146
40	11	103	103	116	102	104

Table 7: Data for 5

S	h	$U1$	$U2$	$U3$	$U4$	$U5$
mm	mm	mV	mV	mV	mV	mV
40	11	106	103	103	104	103
60	31	162	175	153	172	153
100	71	240	252	227	249	284
140	111	320	312	367	328	330
160	131	399	387	361	388	403
200	171	456	450	451	457	411
220	191	464	485	484	486	448
240	211	482	494	514	497	498
280	251	554	555	567	549	550
320	291	606	602	507	569	550
360	331	660	628	645	652	650